

Research Article

Upper and Lower Weaky m_{χ} - $\alpha \psi$ - Continuous Multifunctions

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Abstract

In this paper, we introduce the notion of $m_x - \alpha \psi$ -closed set and investigate some of its properties. We introduce upper/lower $m_x - \alpha \psi$ -continuous, weakly $m_x - \alpha \psi$ -continuous, slightly $m_x - \alpha \psi$ -continuous and almost $m_x - \alpha \psi$ -continuous multifunctions from a set satisfying certain minimal condition into a topological space and also we obtain their characterizations and properties of such multifunctions.

Keywords: Minimal structure; $m_x - \alpha \psi$ -closed set; $m_x - \alpha \psi$ -continuous functions in minimal structure spaces

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Introduction

In 1961, Levine [1] introduced the notion of weakly continuous functions. Popa and Smithson [2,3] independently introduced the concept of weakly continuous multifunctions. Noiri [4] introduced the concept of minimal structure on a nonempty set. Also they introduced the notion of m_x -open set and m_x -closed set and characterize those sets using m_x -cl and m_x -int operators respectively. Further they introduced *m*-continuous functions [5] and studied some of its basic properties. Noiri and Popa [6] introduced and studied other forms of continuous multifunctions namely, slightly m-continuous multifunctions.

In this paper, we introduce $m_x - \alpha \psi$ -closed set and also we study some of the upper/lower $m_x - \alpha \psi$ -continuous multifunctions as the multifunctions are defined between a set satisfying certain minimal condition into a topological space. We obtain some characterizations and some properties of such multifunctions.

Preliminaries

In this section, we introduce the m-structure and define some important subsets associated to the m-structure and the relation between them.

Definition

Let X be a nonempty set and let $m_X \subseteq P(X)$, where P(X) denote the power set of X. Where m_X is an *m*-structure (or a minimal structure) on X, if ϕ and X belong to m_X .

The members of the minimal structure m_X are called m_X -open sets, and the pair (X, m_X) is called an *m*-space. The complement of m_X -open set is said to be m_X -closed.

Definition

[7] Let X be a nonempty set and m_X an m -structure on X. For a subset A of X, m_X -closure of A and m_X -interior of A are defined as follows:

1.
$$m_X - Cl(A) = \bigcap \{F : A \subseteq F, X - F \in m_X\}$$

2.
$$m_X - Int(A) = \bigcup \{F : U \subseteq A, U \in m_X\}$$
.

Lemma

[7] Let X be a nonempty set and m_X an m -structure on X. For

subsets A and B of X, the following properties hold:

1.
$$m_X - Cl(X - A) = X - m_X - Int(A)$$
 and $m_X - Int(X - A) = X - m_X - Cl(A)$.

2. If $(X - A) \in m_X$, then $m_X - cl(A) = A$ and if $A \in m_X$ then $m_X - int(A) = A$.

3.
$$m_X - Cl(\phi) = \phi$$
, $m_X - Cl(X) = X$, $m_X - int(\phi) = \phi$ and $m_X - int(X) = X$.

4. If $A \subseteq B$ then $m_X - Cl(A) \subseteq m_X - Cl(B)$ and $m_X - int(A) \subseteq m_X - int(B)$.

5. $A \subseteq m_X - Cl(A)$ and $m_X - Int(A) \subseteq A$.

6. $m_X - Cl(m_X - Cl(A)) = m_X - Cl(A)$ and $m_X - Int(m_X - Int(A)) = m_X - Int(A)$.

Lemma

[5] Let (X, m_X) be an m-space and A a subset of X. Then $x \in m_X - cl(A)$ if and only if $U \cap A \neq \phi$ for every $U \in m_X$ containing x.

Definition

[7] A minimal structure m_X on a nonempty set X is said to have the property β if the union of any family of subsets belonging to m_X belongs to m_X .

Remark

[8] A minimal structure m_X with the property β coincides with a generalized topology on the sense of Lugojan.

Lemma

[9] Let X be a nonempty set and m_X an *m*-structure on X satisfying the property β . For a subset A of X, the following property hold:

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- 1. $A \in m_X$ iff $m_X int(A) = A$
- 2. $A \in m_X$ iff $m_X cl(A) = A$
- 3. $m_X int(A) \in m_X$ and $m_X cl(A) \in m_X$

Definition

A subset A of an m -space (X, m_X) is called

1. an m_X -preopen set [10] if $A \subseteq U$ - $int(m_X$ - cl(A)) and a m_X -preclosed set if m_X - $cl(m_X$ - $int(A)) \subseteq A$,

2. an m_X -semiopen set [10] if $A \subseteq m_X - cl(m_X - int(A))$ and a m_X -semiclosed set if $m_X - int(m_X - cl(A)) \subseteq A$,

3. an m_X -semi generalized-closed [10] (briefly $m_X - sg$ -closed) set if $m_X - scl(A) \subseteq U$ whenever $A \subseteq U$ and U is m_X -semi-open in (X, m_X) . The complement of an m_X -sg-closed set is called an m_X sg-open set.

The m_X -pre closure (resp. m_X -semi closure, $m_X - \alpha$ -closure) of a subset A of an m-space (X, m_X) is the intersection of all m_X -pre closed (resp. m_X -semi closed, $m_X - \alpha$ -closed) sets that contain Aand is denoted by $m_X - pcl(A)$ (resp. $m_X - scl(A)$, $m_X - m_X$).

$m_x - \alpha \psi$ -closed and $m_x - \alpha \psi$ -open sets

Definition

A subset A of an m-space (X, m_X) is called an

1. $m_X - \alpha$ -open set if $A \subseteq m_X - int(m_X - cl(m_X - int(A)))$ and an $m_X - \alpha$ -closed set if $m_X - cl(m_X - int(m_X - cl(A))) \subseteq A$,

2. $m_X - \psi$ -closed set if $m_X - scl(A) \subseteq U$ whenever $A \subseteq U$ and U is $m_X - sg$ -open in (X, m_X) . The complement of an $m_X - \psi$ -closed set is called an $m_X - \psi$ -open set.

3. $m_X - \alpha \psi$ -closed set if $m_X - \psi cl(A) \subseteq U$ whenever $A \subseteq U$ and U is $m_X - \alpha$ -open in (X, m_X) . The complement of an $m_X - \alpha \psi$ -closed set is called an $m_X - \alpha \psi$ -open set.

Notation

For an *m*-space (X,m_X) , $O(X,m_X)$ (resp. $SO(X,m_X)$), $PO(X,m_X)$, $\alpha O(X,m_X)$, $SGO(X,m_X)$, $\psi O(X,m_X)$, $\alpha \psi$ - $O(X,m_X)$) denotes the class of all open (resp. m_X -semiopen, m_X preopen, $m_X - \alpha$ -open, m_X -sg-open, $m_X - \psi$ -open, $m_X - \alpha \psi$ open) subsets of (X,m_X) .

Definition

Let (X, m_X) be an *m*-space and let *A* be a subset of *X*. Then

1. the intersection of all $m_X - m_X$ -closed sets containing A is called the $m_X - \alpha \psi$ -closure of A and is denoted by $m_X - \alpha \psi$ - cl(A).

2. the union of all $m_X - \alpha \psi$ -open sets that are contained in A is called the $m_X - \alpha \psi$ -interior of A and is denoted by $m_X - \alpha \psi$ - int(A)

Example (1)

Let $X = \{a, b, c, d\}$. Define the *m*-structure on *X* as follows: $m_X = \{\phi, X, \{a\}, \{b\}, \{a, b\}$.

Then $SO(X, m_X) = \{\phi, X, \{a\}, \{b\}, \{a, c\}, \{a, d\}, \{b, d\}, \{a, c, d\}\}$,

 $\alpha O(X, m_X) = \{\phi, X, \{a\}, \{b\}, \{a, b\}, \{a, c\}, \{a, b, c\}\}$ and

 $\alpha \psi - O(X, m_X) = \{ \phi, X, \{a\}, \{b\}, \{c\}, \{a, b\}, \{a, c\}, \{a, d\}, \{b, c\}, \{a, b\}, \{a, c\}, \{a, d\}, \{b, c\}, \{a, b\}, \{a, c\}, \{a,$

 $\{b,d\},\{a,b,c\},\{a,c,d\}\}$.

Example (2)

Let $X = \{a, b, c\}$. Define the *m*-structure on X as follows: $m_X = \{\phi, X, \{a\}, \{b\}\}$.

Then $SO(X, m_X) = \{\phi, X, \{a\}, \{b\}, \{a, c\}, \{b, c\}\}$,

$$\alpha O(X, m_X) = \{\phi, X, \{a\}, \{b\}\} \text{ and } \alpha \psi - O(X, m_X) = P(X).$$

Example (3)

Let $X=\{a,b,c,d\}$. Define the m -structure on X as follows: $m_X=\{\phi,X,\{a\},\{b\},\{a,b,c\},\{a,b,d\}\}$.

Then $SO(X, m_X) = \{\phi, X, \{a\}, \{b\}, \{a, c\}, \{a, d\}, \{a, d\}, \{a, b\}, \{a, c\}, \{a, d\}, \{a, b\}, \{$

 $\{b,c\},\{b,d\},\{a,b,c\},\{a,c,d\},\{b,c,d\}\}$

 $\begin{array}{l} \alpha O(X,m_X) = \{ \phi, X, \{a\}, \{b\}, \{a,b,c\}, \{a,b,d\} \} \text{ and } \\ O(X,m_X) = \{ \phi, X, \{a\}, \{b\}, \{c\}, \{d\}, \{a,b\}, \{a,c\}, \\ \alpha \psi \ - \end{array}$

 $\{a,d\},\{b,c\},\{b,d\},\{c,d\},\{a,b,c\},\{a,c,d\},\{b,c,d\}\}$

Definition

The intersection of all $m_X - \alpha$ -open subsets of (X, m_X) containing A is called the $m_X - \alpha$ -kernel of A (briefly, $m_X - \alpha ker(A)$) i.e. $m_X - \alpha ker(A) = \bigcap \{G \in m_X - \alpha O(X) : A \subseteq G\}$. And $m_X - s ker(A)$, $m_X - sgker(A)$, an $m_X - \psi ker(A)$ are defined similarly.

Theorem (1)

Let A be a subset of (X, m_X) , then A is $m_X - (\alpha, \psi)$ -closed if and only if $m_X - \psi cl(A) \subseteq m_X - \alpha ker(A)$.

Proof

Suppose that A is $m_X - \alpha \psi$ -closed and let $D = \{S : S \subseteq X, A \subseteq S : Sis \ an \ m_X - \alpha \text{ -open} \}$. Then $m_X - \alpha \text{ -open} \}$. Then $m_X - \alpha \text{ -open} \}$. $\alpha \text{ -apen} = \bigcap_{S \in D} S$. Observe that $S \in D$ implies that $A \subseteq S$ follows $m_X - \psi cl(A) \subseteq S$ for all $S \in D$.

Conversely, if $m_X - \psi cl(A) \subseteq m_X - aker(A)$, take $S \in \alpha O(X, m_X)$ such that $A \subseteq S$ then by hypothesis,

 $m_X - \psi cl(A) \subseteq m_X - \alpha ker(A) \subseteq S$.

This shows that A is $m_X - \alpha \psi$ -closed.

Theorem (2)

For subsets A and B of (X, m_X) , the following properties hold:

1. If A is $m_X - \psi$ -closed, then A is $m_X - \alpha \psi$ -closed.

2. If m_X has the property β and A is $m_X - \alpha \psi$ -closed and $m_X - \alpha$ -open then A is $m_X - \psi$ -closed.

3. If A is $m_X - \alpha \psi$ -closed and $A \subseteq B \subseteq \psi cl(A)$ then B is $m_X - \alpha \psi$ -closed.

Proof

1. Let A be an $m_X - \psi$ -closed set in (X, m_X) . Let $A \subseteq U$, where U is $m_X - \alpha$ -open in (X, m_X) . Since A is $m_X - \psi$ -closed, $m_X - \psi cl(A) = A$, $m_X - \psi cl(A) \subseteq U$. Therefore, A is $m_X - \alpha \psi$ -closed.

2. Since A is $m_X - \alpha$ -open and $m_X - \alpha \psi$ -closed, we have $m_X - \psi cl(A) \subseteq A$. Therefore, A is $m_X - \psi$ -closed

3. Let U be an $m_X - \alpha$ -open set of (X, m_X) such that $B \subseteq U$, then $A \subseteq U$. Since A is $m_X - \alpha \psi$ -closed, $m_X - \psi cl(A) \subseteq U$. Now $m_X - \psi cl(B) \subseteq m_X - \psi cl(m_X - \psi cl(A)) \subseteq U$. Therefore, B is also an $m_X - \alpha \psi$ -closed set of (X, m_X) .

Theorem (3)

Union of two $m_X - \alpha \psi$ -closed sets is $m_X - \alpha \psi$ -closed.

Proof

Let A and B be two $m_X - \alpha \psi$ -closed sets in (X, m_X) . Let $A \cup B \subseteq U$, U is $m_X - \alpha$ -open. Since A and B are $m_X - \alpha \psi$ -closed sets, $m_X - \psi cl(A) \subseteq U$ and $m_X - \psi cl(B) \subseteq U$. This implies that $m_X - \psi cl(A \cup B) \subseteq m_X - \psi cl(A) - \psi cl(B) \subseteq U$ and so $m_X - \psi cl(A \cup B) \subseteq U$. Therefore $A \cup B$ is $m_X - \alpha \psi$ -closed.

Theorem (4)

Let m_X be an m-structure on X satisfying the property β and $A \subseteq X$. Then A is an $m_X - \alpha \psi$ -closed set if and only if there does not exist a nonempty $m_X - \alpha$ -closed set F such that $F \neq \phi$ and $F \subseteq m_X - \psi cl(A) - A$.

Proof

Suppose that A is an $m_X - \alpha \psi$ -closed set and let $F \subseteq X$ be an $m_X - \alpha$ -closed set such that $F \subseteq m_X - \psi cl(A) - A$. It follows that, $A \subseteq X - F$ and X - F is an $m_X - \alpha$ -open set. Since A is an $m_X - \alpha \psi cl$ closed set, we have that $m_X - \psi cl(A) \subseteq X - F$ and $F \subseteq X - m_X - \psi cl(A)$. Follows that, $F^+(V) \subset m_X - \psi cl(A) \cap (X - m_X - \psi cl(A)) = \phi$, implying that $F = \phi$.

Conversely, if $A \subseteq U$ and U is an $m_X - \alpha$ -open set, then $m_X - \psi cl(A) \cap (X-U) \subseteq m_X - \psi cl(A) \cap (X-A) = m_X - \psi cl(A) - A$. Since $m_X - \psi cl(A) - A$ does not contain subsets $m_X - \alpha$ -closed sets different from the empty set, we obtain that $m_X - \psi cl(A) \cap (X-U) = \phi$ and this implies that $m_X - \psi cl(A) \subseteq U$ in consequence A is $m_X - \alpha \psi$ -closed.

We can observe that if in Theorem 3.11., the property β is omitted then the result can be false as we can see in the following example.

Example

Let
$$X = \{a, b, c, d\}$$
. The *m*-structure on *X* is defined as
 $m_X = \{\phi, X, \{a\}, \{b\}, \{a, c\}\}$.
 $\alpha C(X, m_X) = \{X, \phi, \{d\}, \{b, d\}, \{c, d\}, \{b, c, d\}, \{b, c, d\}\}$

and $\alpha \psi = \frac{C(X, m_X) = \{X, \phi, \{b\}, \{c\}, \{d\}, \{a, c\}, \{a, d\}, \{b, d\}, \{b, c\}, \{c, d\}, \{b, c, d\}, \{a, c, d\}, \{a, b, d\}\}}{\{b, d\}, \{b, c\}, \{c, d\}, \{b, c, d\}, \{a, c, d\}, \{a, b, d\}\}}$

The set $\{a\}$ is not an $m_X - \alpha \psi$ -closed set and there does not exist

 $m_X - \alpha$ -closed set F such that $F \neq \phi$ and $F \subseteq m_X - \psi cl(A) - A$.

Theorem (5)

Let (X, m_X) be an *m*-space and $A \subseteq X$, then *A* is $m_X - \alpha \psi$ -open if and only if $F \subset m_X - \psi$ int(*A*) where *F* is $m_X - \alpha$ -closed and $F \subset A$. **Proof**

Let A be an $m_X - \alpha \psi$ -open, F be $m_X - \alpha$ -closed set such that $F \subset A$. Then $X - A \subset X - F$, but X - F is $m_X - \alpha$ -closed and X - A is $m_X - \alpha \psi$ -closed implies that $m_X - \psi cl(X - A) \subset X - F$. Follows that $X - m_X - \psi int(A) \subset X - F$. In consequence $F \subset m_X - \psi int(A)$.

Conversely, if F is $m_X - \alpha$ -closed, $F \subset A$ and $F \subset m_X - \psi int(A)$.

Let $X - A \subset U$ where U is $m_X - \alpha$ -open, then $X - U \subset A$ and X - Uis $m_X - \alpha$ -closed. By hypothesis, $X - U \subset m_X - \psi int(A)$. Follows $X - m_X - \psi int(A) \subset U$ but it is equivalent to $m_X - \psi cl(X - A) \subset U$. Therefore, X - A is $m_X - \alpha \psi$ -closed and hence A is $m_X - \alpha \psi$ -open.

Weak $m_X - \alpha \psi$ -continuous and almost $m_X - \alpha \psi$ -continuous multifunctions

Definition (1)

Let (X,m_X) be an *m*-space and (Y,σ) a topological space. A multifunction $F:(X,m_X) \rightarrow (Y,\sigma)$ is said to be

1. upper $m_X - \alpha \psi$ -continuous (resp. upper almost $m_X - \alpha \psi$ -continuous, upper weakly $m_X - \alpha \psi$ -continuous) at a point x if for each open set V of Y containing F(x), there exists an $m_X - \alpha \psi$ -open set U of m_X containing x such that $F(U) \subset V$ (resp. $F(U) \subset int(cl(V)), F(U) \subset cl(V))$,

2. lower $m_X - \alpha \psi$ -continuous (resp. lower almost $m_X - \alpha \psi$ -continuous, lower weakly $m_X - \alpha \psi$ -continuous) at a point $x \in X$ if for each open set V of Y such that $F(x) \cap V \neq \phi$, there exists an m_X - $\alpha \psi$ -open set U of m_X containing x such that $F(u) \cap V \neq \phi$ (resp. $F(u) \cap int(cl(V)) \neq \phi, F(u) \cap cl(V) \neq \phi$) for each $u \in U$,

3. upper/lower $m_X - \alpha \psi$ -continuous (resp. almost $m_X - \alpha \psi$ -continuous, weakly $m_X - \alpha \psi$ -continuous) if it has this property at each point $x \in X$.

Definition (2)

A multifunction $F:(X,m_X) \to (Y,\sigma)$ is said to be almost $m_X - \alpha \psi$ -open if $F(U) \subset int(cl(F(U)))$ for every $m_X - \alpha \psi$ -open set U of m_X .

Theorem (1)

If a multifunction $F:(X,m_X) \rightarrow (Y,\sigma)$ is upper weakly $m_X - \alpha \psi$ -continuous and almost $m_X - \alpha \psi$ -open, then F is upper almost m_X - $\alpha \psi$ -continuous.

Proof

Let V be any open set in Y containing F(x). Then there exists an $m_X - \alpha \psi$ -open set U of m_X containing x such that $F(U) \subset cl(V)$. Since F(x) is almost $m_X - \alpha \psi$ -open, $F(U) \subset int(cl(F(U))) \subset int(cl(V))$. Therefore, F is upper almost $m_X - \alpha \psi$ -continuous.

Theorem (2)

Let $F:(X,m_X) \rightarrow (Y,\sigma)$ be a multifunction such that F(x) is open in Y for each $x \in X$. Then, the following properties are equivalent:

- 1. F is lower $m_X \alpha \psi$ -continuous;
- 2. *F* is lower almost $m_X \alpha \psi$ -continuous;

3. F is lower weakly $m_X - \alpha \psi$ -continuous.

Proof

(i) \Rightarrow (ii) and (ii) \Rightarrow (iii): The proofs of these implications are obvious.

(iii) \Rightarrow (i): Let $x \in X$ and V be any open set such that $F(x) \cap V \neq \phi$. There exists an $m_X - \alpha \psi$ -open set U of m_X such that $F(u) \cap cl(V) \neq \phi$ for each $u \in U$. Since F(u) is open, $F(u) \cap V \neq \phi$ for each $u \in U$ and hence F is lower $m_X - \alpha \psi$ -continuous.

Slightly $m_X - \alpha \psi$ -continuous Multifunctions

Definition

Let (X,m_X) be an *m*-space and (Y,σ) a topological space. A multifunction $F:(X,m_X) \rightarrow (Y,\sigma)$ is said to be

1. upper slightly $m_X - \alpha \psi$ -continuous if for each $A \in m_X$ and each clopen set V of Y containing F(x), there exists an $m_X - \alpha \psi$ -open set U of m_X containing x such that $F(U) \subset V$,

2. lower slightly $m_X - \alpha \psi$ -continuous if for each $x \in X$ and each clopen set V of Y such that $F(x) \cap V \neq \phi$, there exists an $m_X - \alpha \psi$ -open set U of m_X containing x such that $F(u) \cap V \neq \phi$ for each $u \in U$.

Theorem (1)

For a multifunction $F:(X,m_X) \rightarrow (Y,\sigma)$, the following are equivalent:

1. F is upper slightly $m_X - \alpha \psi$ -continuous;

2. $F^+(V) = m_X - \alpha \psi - int(F(V))$ for each $V \in CO(Y)$;

3. $F^{-}(V)$) - $\alpha \psi$ - $cl(F^{-}(V))$ for each $V \in CO(Y)$.

Proof

(i) \Rightarrow (ii): Let *V* be any clopen set of *Y* and $x \in F^+(V)$. Then $F(x) \in V$. There exists an $m_x - \alpha \psi$ -open set *U* of m_x containing *x* such that $F(U) \subset V$. Thus $x \in U \subset F^+(V)$ and hence $x \in m_X - \alpha \psi$ - *int*($F^+(V)$). Therefore, we have $F^+(V) \subset m_X - \alpha \psi$ - *int*($F^+(V)$). But, $m_x - \alpha \psi$ - *int*($F^+(V)$) $\subset F^+(V)$, we obtain $F^+(V) = m_X - \alpha \psi$ - *int*($F^+(V)$).

(ii) \Rightarrow (iii): Let *K* be any clopen set of *Y*. Then *Y*-*K* is clopen in *Y*. By (ii) and Lemma 2.3., we have $X - F^+(K) = (Y - K) = m_X - \alpha \psi - int(F^+(Y - K)) = X - [m_X - \alpha \psi - cl(F^-(K))]$. Therefore, we obtain $F^-(K) = m_X - \alpha \psi - cl(F^-(K))$.

(iii) \Rightarrow (ii): This follows from the fact that $F^{-}(Y-B) = F^{+}(B)$ for every subset *B* of *Y*.

(ii) \Rightarrow (i): Let $x \in X$ and V be any clopen set of Y containing F(x). Then $x \in F^+(V) = m_X - \alpha \psi - int(F^+(V))$. There exists an $m_x - \alpha \psi$ -open set U of m_x containing x such that $x \in U \subset F^+(V)$. Therefore, we have $x \in U$, U is an $m_x - \alpha \psi$ -open set of m_x and $f(U) \subset V$. Hence F is upper slightly $m_x - \alpha \psi$ -continuous.

Theorem (2)

For a multifunction $F:(X,m_X) \rightarrow (Y,\sigma)$, the following are equivalent:

1. *F* is lower slightly $m_x - \alpha \psi$ -continuous;

2. $F^{-}(V) = m_X - \alpha \psi - int(F^{-}(V))$ for each $V \in CO(Y)$;

3. $F^+(V) = m_X - \alpha \psi - cl(F^+(V))$ for each $V \in CO(Y)$.

Proof

(i) \Rightarrow (ii): Let $V \in CO(Y)$ and $x \in F^-(V)$. Then $F(x) \cap V \neq \phi$ and by (i) there exists an $m_x - \alpha \psi$ -open set U of m_x containing x such that $F(u) \cap V \neq \phi$ for each $u \in U$. Therefore, we have $U \subset F^-(V)$ and hence $x \in U \subset m_X - \alpha \psi$ - $int(F^-(V))$. Thus, we obtain $F^-(V) \subset m_X - \alpha \psi$ - $int(F^-(V))$ and by Lemma 2.3., $F^-(V) = m_X - \alpha \psi$ - $int(F^-(V))$.

(ii) \Rightarrow (iii): Let $V \in CO(Y)$. Then $Y - V \in CO(Y)$ and by (ii) we have $X - F^+(V) = F^-(Y - V) = m_X - \alpha \psi - int(F^-(Y - V)) = X - m_X - m_$

J Appl Computat Math ISSN: 2168-9679 JACM, an open access journal $\alpha \psi - cl(F^+(V))$. Hence we obtain $F^+(V) = m_X - \alpha \psi - cl(F^+(V))$.

(iii) \Rightarrow (i): Let x be any point of X and V any clopen set of Y such that $F(x) \cap V \neq \phi$. Then $x \in F^-(V)$ and $x \notin X - F^-(V) = F^+(Y - V)$. By (iii), we have $x \notin m_X - \alpha \psi - cl(F^+(Y - V))$. By Lemma 2.4., there exists an $m_X - \alpha \psi$ -open set of m_x containing x such that $U \cap F^+(Y - V) = \phi$, hence $U \subset F^-(V)$. Therefore, $F(u) \cap V \neq \phi$ for each $u \in U$ and F is lower slightly $m_x - \alpha \psi$ -continuous.

Corollary (1)

For a multifunction $F:(X,m_X) \rightarrow (Y,\sigma)$, where m_x has the property β , the following are equivalent:

1. F is upper slightly $m_x - \alpha \psi$ -continuous;

2. $F^+(V)$ is $m_x - \alpha \psi$ -open in (X, m_x) for each $V \in CO(Y)$;

3. $F^{-}(V)$ is $m_{x} - \alpha \psi$ -closed in (X, m_{X}) for each $V \in CO(Y)$.

Corollary (2)

For a multifunction $F:(X,m_X) \rightarrow (Y,\sigma)$, where m_x has the property β , the following are equivalent:

1. F is lower slightly $m_x - \alpha \psi$ -continuous;

2. $F^{-}(V)$ is $m_x - \alpha \psi$ -open in (X, m_X) for each $V \in CO(Y)$;

3. $F^+(V)$ is $m_x - \alpha \psi$ -closed in (X, m_X) for each $V \in CO(Y)$.

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