The Improved exp(−ϕ(ξ)) Fractional Expansion Method and its Application to Nonlinear Fractional Sharma-Tasso-Olver Equation

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Abstract

In this paper, we propose a new method called exp(−ϕ(ξ)) fractional expansion method to seek traveling wave solutions of the nonlinear fractional Sharma-Tasso-Olver equation. The result reveals that the method together with the new fractional ordinary differential equation is a very influential and effective tool for solving nonlinear fractional partial differential equations in mathematical physics and engineering. The obtained solutions have been articulated by the hyperbolic functions, trigonometric functions and rational functions with arbitrary constants.

Keywords: Improved exp(−ϕ(ξ))fractional expansion method; Nonlinear fractional Sharma-Tasso-Olver equation

Introduction

It is well known that nonlinear fractional partial differential equations (NFPDEs) are widely used as models to describe many important complex physical phenomena in various fields of science, such as plasma physics, nonlinear optics, solid state physics, fluid mechanics, fluid flow, chemical kinematics, chemistry, biology, finance, economy, and so on. Thus, establishing exact traveling wave solutions of NFPDEs is very important to better understand nonlinear phenomena's as well as other real-life applications.

In the past, a wide range of methods have been developed to generate analytical solutions of nonlinear partial differential equations. Among these methods are the $\left(\frac{G'}{G}\right)$ expansion method [1,2], the $\left(\frac{G'}{G},\frac{1}{G}\right)$ expansion method [3], the generalized of exp (−ϕ(ξ) expansion method [4,5],the coth a (ξ) expansion method [6], the F-expansion method [7], and various other methods [8-11].

In recent years, several attempts have succeeded in the synthesis of the previous methods to searching for exact solutions to nonlinear fractional differential equations. Zhang and Zhang [12-14] proposed on the basis of homogeneous balance principle and Jumarie's modified Riemann-Liouville derivative a new direct method called fractional sub-equation method to search for explicit solutions of nonlinear time fractional biological population model and (4+1) dimensional space-time fractional Fokas equation. Wangi and Xu [15] improved this method to obtain the exact solutions of the space-time fractional generalized Hirota-Satsuma coupled Korteweg-de Vries equations.

In this paper, we propose the improved exp (−ϕ(ξ)) fractional expansion method for obtaining novel and more general exact traveling wave solutions for the nonlinear fractional Sharma Tasso-Olver equation [12,13]:

$$D_t^\alpha u + 3\delta u^2 D_x^\alpha u + 3\delta (D_x^\alpha u)^2 + 3\delta u D_x^{2\alpha} u + \delta D_x^{3\alpha} u = 0 \cdot$$

where 0<α≤1,u=u(x,t),t>0,δ is constant.

The remainder of the paper is organized as follows. Section 2 gives some definitions and properties of the modified Riemann-Liouville derivative [16], and explains the improved exp (−ϕ(ξ)) fractional expansion method. Section 3 applies this method for solving the nonlinear fractional Sharma-Tasso-Olver equation. Section 4 concludes the paper.

Jumarie's Modified Riemann-Liouville Derivative and the Improved exp(−ϕ(ξ))Fractional Expansion Method

In this section, we briefly review the main definitions and properties of the fractional calculus proposed by Jumarie [17] which will be used in the following section.

The modified Riemann-Liouville derivative as defined by Jumarie [18] is:

$$D_t^\alpha f(\text{t}) = \begin{cases} \dfrac{1}{\Gamma(1-\alpha)} \dfrac{d}{dt}\int_0^t (\text{t}-\xi) - f(0)\,\mathrm{d}\xi, 0<\alpha\le 1 \\ \left[f^{[n]}(t)^{(\alpha-n)}, n\le\alpha<n+1, n\ge 1 \right] \end{cases} \quad (2.1)$$

Some useful formulas and properties of Jumarie's modified Riemann-Liouville derivative were summarized in [18], among them the three following formulas:

$$D_t^\alpha t^r = \frac{\Gamma(1+r)}{\Gamma(1+r-\alpha)} t^{r-\alpha}, r > 0 \quad (2.2)$$

$$D_t^\alpha f\left[f(t)g(t)\right] = g(t) D_t^\alpha f(\text{t}) D_t^\alpha g(\text{t}) \quad (2.3)$$

$$D_t^\alpha f(g(t)) = \int_g^t [g(t)] D_t^\alpha f(g(\text{t}) = D_t^\alpha f(g(\text{t})\left(g_t^{''}(t)\right)^\alpha \quad (2.4)$$

Now, we outline the main steps of the exp(−ϕ(ξ)) fractional expansion method to solve fractional differential equations. Suppose that a fractional partial differential equation, say in the independent variables x and t, is given by

$$F\left(u, u_t, u_x, D_x^\alpha u\right) = 0, 0 < \alpha \le 1 \quad (2.5)$$

Where u=u(x,t) is an unknown function, F is a polynomial in

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u=u(x,t) and their various partial derivatives including fractional derivatives, $D_t^\alpha u$ and $D_x^\alpha u$ are the modified Riemann Liouville derivatives of u with respect to t and x, respectively. The main steps of this method are as follows:

Step 1: Use the traveling wave transformation:

$$u(x,t) = u(\xi), \ \xi = x + kt \tag{2.6}$$

Where k is a non-zero constant to be determined latter, which reduces (2.5) to an (NFODE) for u=u(ξ) in the form:

$$P\left(u, u_\xi, k_{u\xi}, D_\xi^\alpha u, k^\alpha, D_\xi^\alpha u, \ldots\right) = 0, 0 < \alpha \le 1 \tag{2.7}$$

Step 2: Balance the highest derivative term with the nonlinear terms in (2.7) to find the value of the positive integer (m). If the value (m) is non-integer one can transform the equation studied.

Step 3: Suppose that the solution of (2.7) can be expressed as follows:

$$u(\xi) = \sum_{i=-m}^{-1} \alpha_i \left(\exp(-\phi(\xi))\right)^i + \alpha_0 + \sum_{i=1}^{m} \alpha_i \left(\exp(-\phi(\xi))\right)^i \tag{2.8}$$

Where, α_i (i=0,1,...,m) are constants to be determined, such that αi0 and ϕ(ξ) satisfies the following fractional differential equation:

$$D_\xi^\alpha \phi(\xi) = \exp(-\phi(\xi)) + \mu \exp(\phi(\xi)) + \lambda \tag{2.9}$$

eqn. (2.9) gives the following solutions:

Family 1: When μ≠0,(λ²−4μ)>0,

$$\phi_1(\xi) = In\left(\frac{-\sqrt{(\lambda^2 - 4\mu)} \tanh\left(\frac{\sqrt{(\lambda^2 - 4\mu)}}{2}\left(\frac{\xi^\alpha + c\Gamma(1+\alpha)}{\Gamma(1+\alpha)}\right)\right) - \lambda}{2\mu}\right) \tag{2.10}$$

Family 2: When μ≠0, (λ²−4μ)<0,

$$\phi_2(\xi) = In\left(\frac{-\sqrt{(4\mu - \lambda^2)} \tanh\left(\frac{\sqrt{(4\mu - \lambda^2)}}{2}\left(\frac{\xi^\alpha + c\Gamma(1+\alpha)}{\Gamma(1+\alpha)}\right)\right) - \lambda}{2\mu}\right) \tag{2.11}$$

Family 3: When μ=0,λ≠0,(λ²−4μ)>0,

$$\phi_3(\xi) = In\left(\frac{\lambda}{\exp\left(\lambda\left(\frac{\xi^\alpha + c\Gamma(1+\alpha)}{\Gamma(1+\alpha)}\right)\right) - 1}\right) \tag{2.12}$$

Family 4: When μ ≠0,λ ≠ 0,(λ²−4μ)=0,

$$\phi_4(\xi) = In\left(\frac{2\lambda\left(\frac{\xi^\alpha + c\Gamma(1+\alpha)}{\Gamma(1+\alpha)}\right) + 4}{\lambda^2\left(\frac{\xi^\alpha + c\Gamma(1+\alpha)}{\Gamma(1+\alpha)}\right)}\right) \tag{2.13}$$

Family 5: When μ=0,λ=0,(λ²−4μ)=0,

$$\phi_5(\xi) = In\left(\frac{\xi^\alpha + c\Gamma(1+\alpha)}{\Gamma(1+\alpha)}\right) \tag{2.14}$$

Step 4: Substituting (2.8) into (2.7) and using (2.9), and then

setting all the cofficients of $(\exp(-\phi(\xi)))^i$ of the resulting systems to zero, yields a system of algebraic equations for k,λ,μ and α_i (i=−m,...,m).

Step 5: Suppose that the value of the constants k, λ,μ and α_i (i=−m,...,m) can be found by solving the algebraic equations which are obtained in Step 4. Since the general solutions of (2.9) have been well known, substituting k,λ,μ,α_i and the solutions of (2.9) into (2.8), we obtain the exact solutions for eqn. (2.5).

Note that if α=1, then eqn. (2.9) becomes ϕ(ξ)=exp(−ϕ(ξ))+μ exp (ϕ(ξ))+λ, which is the foundation of the known exp(−ϕ(ξ)) expansion method for solving partial differential equations (PDEs). Thus, the above described exp(−ϕ(ξ)) fractional expansion method is the extension of the exp (−ϕ(ξ)) method to fractional case.

The Exact Solution for Nonlinear Fractional Sharma Tasso-Olver Equation

In this section, we will apply the improved exp(−ϕ(ξ)) fractional expansion method to find the exact solutions of the nonlinear fractional Sharma-Tasso-Olver equation:

$$D_t^\alpha u + 3\delta u^2 D_x^\alpha u + 3\delta(D_x^\alpha u)^2 + 3\delta u D_x^{2\alpha} u + \delta D_x^{3\alpha} u = 0 \tag{3.1}$$

where 0<α≤1. In ref. [19], the authors solved eqn. (3.1) by a proposed fractional sub-equation method based on the fractional Riccati equation $D_\xi^\alpha \phi(\xi) = r + q\phi(\xi) + p\phi(\xi)^2$.

Now we will apply the described method in Section 2 to eqns. (3.1). To do so, Suppose that

$$u(x,t)=u(\xi), \xi=x+kt, \tag{3.2}$$

where k is a constant. Substituting (3.2) into eqn. (3.1), gives the following nonlinear fractional ordinary differential equations:

$$k^\alpha D_\xi^\alpha u + 3\delta u^2 D_\xi^\alpha u + 3\delta(D_\xi^\alpha u)^2 + 3\delta u^2 D_\xi^{2\alpha} u + \delta D_\xi^{3\alpha} u = 0. \tag{3.3}$$

Suppose that eqn. (3.3) has the following solution:

$$u(\xi) = \sum_{i=-m}^{-1} \alpha_i \left(\exp(-\phi(\xi))\right)^i + \alpha_0 + \sum_{i=1}^{m} \alpha_i \left(\exp(-\phi(\xi))\right)^i \tag{3.4}$$

where α_i (i=−m,...,m) are constants to be determined later. Balancing the order of $D^{3\alpha}_\xi u$ and $u^2 D^\alpha_\xi u$, we find m=1. So,

$$u(\xi)=\alpha_0+\alpha1 \exp(-\phi(\xi))+\alpha_{-1} (\exp(-\phi(\xi)))^{-1} \tag{3.5}$$

Substituting eqns. (3.5) and (2.9) into eqn. (3.3), the left-hand side is converted into polynomials in $(\exp(-\phi(\xi)))^{\pm j}$, (j=0,1,2,....). By collecting each coefficient of these resulted polynomials to zero, we obtain a set ofsimultaneous algebraic equations, which are not presented for sake of clarity, for $\alpha_0,\alpha_1,\alpha_{-1},\lambda,\mu$ and k. Solving these algebraic equations with the help of algebraic software Maple, we obtain:

Case 1: α_0=0,α_1=1,α_{-1}=−μ,λ=λ,μ=μ,k= $k = \exp\left(\frac{In(-\delta(\lambda^2 - 4\mu)}{\alpha}\right)$ (3.6)

Substituting eqn. (3.6) into eqn. (3.5), we have:

$$u(\xi)=\exp(-\phi(\xi))-\mu \exp(\phi(\xi)) \tag{3.7}$$

Where $\xi = x + \exp\left(\frac{In(-\delta(\lambda^2 - 4\mu)}{\alpha}\right)t$

Consequently, the exact solution of the of the nonlinear fractional Sharma-Tasso-Olver equation (3.1) with the help of eqn. (2.10) to eqn. (2.14), are obtained in the following form:

Case (1-1): When μ≠0,(λ²−4μ)>0,

$$u_1(\xi) = \begin{cases} \exp\left(-\left(In\left[-\dfrac{-\sqrt{(\lambda^2-4\mu)}\tanh\left(\dfrac{\sqrt{(\lambda^2-4\mu)}}{2}\left(\dfrac{\xi^\alpha+c\Gamma(1+\alpha)}{\Gamma(1+\alpha)}\right)\right)-\lambda}{2\mu}\right]\right)\right) \\[1em] -\mu\exp\left(In\left[-\dfrac{-\sqrt{(\lambda^2-4\mu)}\tanh\left(\dfrac{\sqrt{(\lambda^2-4\mu)}}{2}\left(\dfrac{\xi^\alpha+c\Gamma(1+\alpha)}{\Gamma(1+\alpha)}\right)\right)-\lambda}{2\mu}\right]\right) \end{cases} \quad (3.8)$$

$$\xi = x + \exp\left(\dfrac{In(-\delta(\lambda^2-4\mu))}{\alpha}\right)t$$

Case (1-2): When μ≠0,(λ²−4μ)<0,

$$u_2(\xi) = \begin{cases} \exp\left(-In\left[-\dfrac{-\sqrt{(4\mu-\lambda^2)}\tan\left(\dfrac{\sqrt{(4\mu-\lambda^2)}}{2}\left(\dfrac{\xi^\alpha+c\Gamma(1+\alpha)}{\Gamma(1+\alpha)}\right)\right)-\lambda}{2\mu}\right]\right) \\[1em] -\mu\exp\left(In\left[-\dfrac{-\sqrt{(4\mu-\lambda^2)}\tanh\left(\dfrac{\sqrt{(4\mu-\lambda^2)}}{2}\left(\dfrac{\xi^\alpha+c\Gamma(1+\alpha)}{\Gamma(1+\alpha)}\right)\right)-\lambda}{2\mu}\right]\right) \end{cases} \quad (3.9)$$

$$\xi = x + \exp\left(\dfrac{In(-\delta(\lambda^2-4\mu))}{\alpha}\right)t$$

Case (1-3): When μ=0,λ≠0,(λ²−4μ)>0,

$$\begin{cases} u_3(\xi) = \exp\left(In\left[\dfrac{\lambda}{\exp(\lambda\left(\dfrac{\xi^\alpha+c\Gamma(1+\alpha)}{\Gamma(1+\alpha)}\right))-1}\right]\right) \\[1em] \xi = x + \exp\left(\dfrac{In(-\delta\lambda^2)}{\alpha}\right)t \end{cases} \quad (3.10)$$

Case (2): $\alpha_0=\alpha_0, \alpha_1=1, \alpha_{-1}=0, \lambda=\lambda, \mu=\mu, k=$ $k=In\left(\dfrac{In(-\delta(3\alpha_0^2-3\alpha_0^2\lambda+\lambda^2-\mu))}{\alpha}\right)$ (3.11)

Substituting (3.11) into (3.5), we have:

$$u(\xi)=\alpha_0+\exp(-\phi(\xi)), \quad (3.12)$$

Where $\xi = x + \exp\left(\dfrac{In(-\delta(3\alpha_0^2-3\alpha_0^2\lambda+\lambda^2-\mu))}{\alpha}\right)$

Consequently, the exact solution of the of the nonlinear fractional Sharma-Tasso-Olver equation (3.1) with the help of eqn. (2.10) to eqn. (2.14), are obtained in the following form:

Case (2-1): When μ≠0,(λ²−4μ)>0,

$$\begin{cases} u_4(\xi)=\alpha_0+\exp\left(-In\dfrac{(\lambda^2-4\mu)\tanh(\dfrac{\sqrt{(\lambda^2-4\mu)}}{2}\left(\dfrac{\xi^\alpha+c\Gamma(1+\alpha)}{\Gamma(1+\alpha)}\right))-\lambda}{2\mu}\right) \\[1em] \xi = x + \exp\left(\dfrac{In(-\delta(3\alpha_0^2-3\alpha_0^2\lambda+\lambda^2-\mu))}{\alpha}\right)t \end{cases} \quad (3.13)$$

Case (2-2): When μ≠0,(λ² 4μ)<0

$$u_5(\xi)=\alpha_0+\exp\left(-In\dfrac{(4\mu-\lambda^2)\tan(\dfrac{\sqrt{(4\mu-\lambda^2)}}{2}\left(\dfrac{\xi^\alpha+c\Gamma(1+\alpha)}{\Gamma(1+\alpha)}\right))-\lambda}{2\mu}\right)$$

$$\xi = x + \exp\left(\dfrac{In(-\delta(3\alpha_0^2-3\alpha_0^2\lambda+\lambda^2-\mu))}{\alpha}\right)t \quad (3.14),$$

Case (2-3): When μ=0,λ≠0,(λ²−4μ)>0

$$\begin{cases} u_6(\xi)=\alpha_0+\exp\left(\left(In\left(\dfrac{\lambda}{\exp(\lambda\left(\dfrac{\xi^\alpha+c\Gamma(1+\alpha)}{\Gamma(1+\alpha)}\right))-1}\right)\right)\right) \\[1em] \xi = x + \exp\left(\dfrac{In(-\delta(3\alpha_0^2-3\alpha_0^2\lambda+\lambda^2-\mu))}{\alpha}\right)t \end{cases} \quad (3.15)$$

Case (2-4): When μ≠0,λ≠0,(λ²−4μ)=0,

$$\begin{cases} u_7(\xi)=\alpha_0+\exp\left(\left(-In\left(\dfrac{2\lambda\left(\dfrac{\xi^\alpha+c\Gamma(1+\alpha)}{\Gamma(1+\alpha)}\right)+4}{\lambda^2\left(\dfrac{\xi^\alpha+c\Gamma(1+\alpha)}{\Gamma(1+\alpha)}\right)}\right)\right)\right) \\[1em] \xi = x + \exp\left(\dfrac{In(-\delta(3\alpha_0^2-3\alpha_0^2\lambda+\lambda^2-\mu))}{\alpha}\right)t \end{cases} \quad (3.16)$$

Case (2-5): When μ=0,λ=0,(λ²−4μ)=0,

$$\begin{cases} u_8(\xi)=\alpha_0+\exp\left(\left(-In\left(\dfrac{\xi^\alpha+c\Gamma(1+\alpha)}{\Gamma(1+\alpha)}\right)\right)\right) \\[1em] \xi = x + \exp\left(\dfrac{In(-3\delta\alpha_0^2)}{\alpha}\right)t \end{cases} \quad (3.17)$$

Case (3): $\alpha_0=\lambda, \alpha_1=2, \alpha_{-1}=0, \lambda=\lambda, \mu=\mu, k=\exp\left(\dfrac{In(-\delta(\lambda^2-4\mu))}{\alpha}\right)$ (3.18)

Substituting (3.18) into (3.5), we have:

$$U(\xi)=\lambda+2\exp(-\phi(\xi)), \quad (3.19)$$

Where $\xi = x + \exp\left(\dfrac{In(-\delta(\lambda^2-4\mu))}{\alpha}\right)$.

Consequently, the exact solution of the of the nonlinear fractional Sharma-Tasso-Olver equation (3.1) with the help of eqn. (2.10) to eqn. (2.14), are obtained in the following form:

Case (3-1): When μ≠0, (λ²−4μ)>0,

$$\begin{cases} u_9(\xi)=\lambda+2\exp\left(-In\dfrac{\lambda^2-4\mu\tan(\dfrac{\sqrt{(\lambda^2-4\mu)}}{2}\left(\dfrac{\xi^\alpha+c\Gamma(1+\alpha)}{\Gamma(1+\alpha)}\right))-\lambda}{2\mu}\right) \\[1em] \xi = x + \exp\left(\dfrac{In(-\delta(\lambda^2-4\mu))}{\alpha}\right)t \end{cases} \quad (3.20)$$

Case (3-2): When μ≠0, (λ²−4μ)<0,

$$u_{10}(\xi) = \lambda + 2\exp\left(-In\frac{\left(\frac{\sqrt{(4\mu-\lambda^2)}}{2}\tan(\frac{\sqrt{(4\mu-\lambda^2)}}{2}\left(\frac{\xi^\alpha+c\Gamma(1+\alpha)}{\Gamma(1+\alpha)}\right)-\lambda\right)}{2\mu}\right) \quad (3.21)$$

$$\xi = x + \exp\left(\frac{In(-\delta(\lambda^2-4\mu))}{\alpha}\right)t$$

Case (3-3): When μ=0, λ≠0,(λ²−4μ)>0,

$$u_{11}(\xi) = \lambda + 2\exp\left(-In\left(\frac{\lambda}{\exp\left(\lambda\left(\frac{\xi^\alpha+c\Gamma(1+\alpha)}{\Gamma(1+\alpha)}\right)-1\right)}\right)\right) \quad (3.22)$$

$$\xi = x + \exp\left(\frac{In(-\delta\lambda^2)}{\alpha}\right)t$$

Case (4): $\alpha_0=\alpha_0, \alpha_1=0, \alpha_{-1}=-\mu\lambda=\lambda, \mu=\mu, k=\exp\left(\exp\frac{In(\delta(\mu-\lambda^2-3\alpha_0^2-3\lambda\alpha_0)}{\alpha}\right)$ (3.23)

Substituting (3.23) into (3.5), we have:

$$u(\xi)=\alpha_0 - \mu(\exp(-\phi(\xi)))^{-1} \quad (3.24)$$

Where $\exp\frac{In(\delta(\mu-\lambda^2-3\alpha_0^2-3\lambda\alpha_0)}{\alpha}$

Consequently, the exact solution of the of the nonlinear fractional Sharma-Tasso-Olver equation (1. 1) with the help of eqn. (2.10) to eqn. (2.14), are obtained in the following form:

Case (4-1): When μ/= 0, (λ2 −4μ) > 0,

$$u_{12}(\xi) = \alpha_0 - \mu\left(\exp\left(-In\left(\frac{\left(-\sqrt{(\lambda^2-4\mu)}\tan\left(\frac{\sqrt{(\lambda^2-4\mu)}}{2}\right)\left(\frac{\xi^\alpha+c\Gamma(1+\alpha)}{\Gamma(1+\alpha)}\right)-\lambda\right)}{2\mu}\right)\right)^{-1}\right) \quad (3.25)$$

$$\xi = x + \exp\frac{In(\delta(\mu-\lambda^2-3\alpha_0^2-3\lambda\alpha_0)}{\alpha}t$$

Case (4-2): When μ≠0, (λ²−4μ)<0,

$$u_{13}(\xi) = \alpha_0 - \mu\left(\exp\left(-In\left(\frac{\left(-\sqrt{(4\mu-\lambda^2)}\tan\left(\frac{\sqrt{(4\mu-\lambda^2)}}{2}\right)\left(\frac{\xi^\alpha+c\Gamma(1+\alpha)}{\Gamma(1+\alpha)}\right)-\lambda\right)}{2\mu}\right)\right)^{-1}\right) \quad (3.26)$$

$$\xi = x + \exp\frac{In(\delta(\mu-\lambda^2-3\alpha_0^2-3\lambda\alpha_0)}{\alpha}t$$

Case (4-3): When μ ≠ 0, λ ≠ 0,(λ² −4μ)=0,

$$u_{14}(\xi) = \alpha_0 - \mu\left(\exp\left(-In\left(\frac{2\lambda\left(\frac{\xi^\alpha+c\Gamma(1+\alpha)}{\Gamma(1+\alpha)}\right)+4}{\left(\lambda^2\left(\frac{\xi^\alpha+c\Gamma(1+\alpha)}{\Gamma(1+\alpha)}\right)\right)}\right)\right)^{-1}\right) \quad (3.27)$$

$$\xi = x + \exp\left(\frac{In(-3\delta(\frac{1}{4}\lambda^2+\alpha_0^2+\lambda\alpha_0)}{\alpha}\right)t$$

Case (5): $\alpha_0=-\lambda, \alpha_1=0, \alpha_{-1}=-2\mu, \lambda=\lambda, \mu=\mu,$ $k = \exp\left(\frac{In(-\delta(\lambda^2-4\mu)}{\alpha}\right)$ (3.28)

Substituting (3.28) into (3.5), we have:

$$U(\xi)=\alpha_0-2\mu(\exp(-\phi(\xi)))^{-1}. \quad (3.29)$$

Where $\xi = x + \exp\left(\frac{In(-\delta(\lambda^2-4\mu)}{\alpha}\right)t$

Consequently, the exact solution of the of the nonlinear fractional Sharma-Tasso-Olver equation (3.1) with the help of eqn. (2.10) to eqn. (2.14), are obtained in the following form

Case (5-1): When μ≠ 0, (λ² −4μ) > 0,

$$u_{15}(\xi) = \alpha_0 - 2\mu\left(\exp\left(-In\left(\frac{\left(-\sqrt{(\lambda^2-4\mu)}\tan\left(\frac{\sqrt{(\lambda^2-4\mu)}}{2}\right)\left(\frac{\xi^\alpha+c\Gamma(1+\alpha)}{\Gamma(1+\alpha)}\right)-\lambda\right)}{2\mu}\right)\right)^{-1}\right) \quad (3.30)$$

$$\xi = x + \exp\frac{In(\delta(\lambda^2-4\mu)}{\alpha}t$$

Case (5-2): When μ≠0, (λ²−4μ)<0,

$$u_{16}(\xi) = \alpha_0 - 2\mu\left(\exp\left(In\left(\frac{\left(-\sqrt{(4\mu-\lambda^2)}\tan\left(\frac{\sqrt{(4\mu-\lambda^2)}}{2}\right)\left(\frac{\xi^\alpha+c\Gamma(1+\alpha)}{\Gamma(1+\alpha)}\right)-\lambda\right)}{2\mu}\right)\right)^{-1}\right) \quad (3.31)$$

$$\xi = x + \exp\frac{In(\delta(\lambda^2-4\mu)}{\alpha}t$$

Conclusion

In this article, we proposed a new method called improved exp (−φ(ξ)) fractional expansion method using the generalized wave transformation (2.6) and the auxiliary fractional differential equation (2.9), to obtain the exact solutions of nonlinear fractional Sharma-Tasso-Olver equation. The main advantage of this method is its capability of greatly reducing the size of computational work compared to existing techniques. The method could be used for a large class of very interesting nonlinear equations. These solutions have rich local structures, it may be important to explain some physical phenomena. This work shows that, the improved exp (−φ(ξ)) fractional expansion method is direct, effective and can be used for many other FNLPDEs in mathematical physics.

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