

## Seismic Analysis of Indoor Auditorium

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### Abstract

The project titled "Seismic analysis of Indoor Auditorium" has been taken up with an objective to determine the seismic response and behaviour of an Auditorium constructed in Chennai area. Even though Chennai is considered as least prone to major earthquake, it is expected that a structure would survive major earthquakes without collapse that might occur unexpectedly during the life of the building. It should also be noted that after the Bhuj earthquake, Indian Standard IS: 1893 was revised and Chennai city was upgraded from zone II to zone III which leads to a substantial increase of the design ground motion parameters. Hence, this project presents an exploratory analysis of the seismic performance of multi-storey buildings system built in the specified area with a comparative study of the structures under past major earthquakes. Computer modeling is undertaken using Ansys is a multi-purpose software which enables to run and simulate tests or working conditions. It also helps in determining and improving weak points, computing by 3D simulations in virtual environment.

**Keywords:** Auditorium; Analysis; Ansys; Earthquake; Seismic; Finite element analysis; Static analysis

### Introduction

An auditorium is a room built to enable the audience to hear and watch performances at venues such as theatres. Generally, an auditorium has an increasing sloped-styled seating, So as to allow the audience at the back of the auditorium to see the stage without any disturbances. The structural design of an auditorium should be a sloped foundation so as to follow the seating layout. Seismic analysis of an auditorium is done using Ansys and various seismic modes and data are collected. The member with the highest deflection is pointed out and strengthening methods can be carried out in the next project [1,2].

### Objective of the Project

- To create a 3-D finite element model
- Analyse the element using Static structural analysis, Modal analysis and Response spectrum analysis
- Find out the member with maximum displacement due to seismic activity.

### Methodology

#### Finite element program

The ANSYS program is a computer program for Finite element analysis and design. Also used to find out how a given design works under operating conditions. It has its own integrate pre and post processor. Ansys program can be used in all disciplines of engineering-structural, mechanical, electrical, electromagnetic, electronic, thermal, and fluid.

#### Basic concepts in FEA

Stress analysis one of the engineering discipline helps in determining stress in materials and structures that are subjected to static or dynamic forces.

The aim of this analysis is to determine the collection of elements, which is also referred as a structure, can safely withstand the specified forces. This can be achieved when the determined stress from the applied forces are less than the ultimate tensile strength and the ultimate compressive strength the material is known to be able to withstand, inspite of that a factor of safety is applied in design.

The factor of safety is one of the important design requirements for any structure based on uncertainty in loads, material strength (yield and ultimate), and consequences of failure. The factor of safety is to prevent detrimental deformations and the factor of safety on ultimate strength is to prevent collapse. The factor of safety is used to calculate the maximum allowable stress [3].

Factor of Safety = Ultimate Tensile Strength/Maximum allowable stress

When performing stress analysis, a factor of safety is calculated to compare with the required factor of safety. The factor of safety is a design requirement given to the stress analyst. The Analyst calculates the design factor. Margin of safety is another way to express the design factor.

Design Factor = Ultimate Tensile Strength/Maximum Calculated Tensile Stress. A key part of analysis involves determining the type of loads acting on a structure, including tension, compression, shear, torsion, bending, or combinations of such loads.

### Problem definition

The finite element method is a numerical method for solving problems of engineering and mathematical physics. It is useful for problems with complicated geometries, loadings, and material properties where analytical solutions cannot be obtained [4].

FEA is a technique that discretizes a given physical or mathematical problem into smaller fundamental parts called elements. An analysis of each element is conducted. A solution to the problem as a whole is obtained by assembling the individual solutions of the elements. Complex problems can be tackled by dividing the problem into smaller and simpler problems that can be solved using existing mathematical tools.

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## Steps in finite element modeling

- Discretize and Select Element Types
- Select a Displacement Function
- Define the Stress/Strain Relationships
- Derive the Element Stiffness Matrix and Equations
- Assemble the Element Equations to obtain the Global Equations
- Solve for the Unknown Displacements
- Solve for the Element Strains and Stresses
- Interpret the Results.

## Finite element meshing of auditorium

Grid generation is the first step of analysis. Grid generation usually requires simplification and idealization of the design model. This requirement is the most cumbersome aspect of grid generation process. Therefore, the analysis model is often rebuilt from scratch, based upon the judgment of skilled analysts in removing details from the design, and duplicating much of the work in creating the geometry. Often, integrated tools are interactive and require the design engineer to provide complex input.

The geometrical question in a finite-element analysis is represented by collection of finite elements used and is known as mesh. Creating the mesh is often the most difficult part of finite element modelling. As a result, the grid generation process is not yet a 'push button' process; it is the most labor-intensive and time-consuming aspect of the computational structural dynamics. It takes too many man-hours and calendar days, and it requires a grid specialist. Mesh generation could be performed graphically, drawing lines on a computer to form elements. Techniques such as extruding a shell mesh to create a solid mesh were developed for creating complex geometric models. With use of solid modelling CAD programs, the geometry to be used in finite element analysis already exists in some format. This geometry can be used for simulation, only if the programs being used have the interface capabilities. Once we have created the geometry in the system, the finite element programs create some type of automatic meshing. In beam elements it is the process of breaking up bigger line entities into smaller line entities. In 2D elements, flat surfaces must be broken into the elements having three or four sides. In shell elements, 3D surfaces must be equally divided into the shell elements. In solid elements, a particular volume must be sectioned into elements. Automatic meshing capabilities directs the user place the elements. Most automatic mashers create tetrahedral elements in solid volumes. Tetrahedral elements can be less in accuracy compared to brick elements. But structural dynamics analysis tetrahedral mesh is sufficient. Structural analysis using Finite Element Method gives a preliminary assessment of dynamic behavior of mechanical structures in order to establish the guidelines for designing the experiment. The main objective of this study was to develop a methodology of seismic analysis of electronic cabinets using ANSYS. Generally has two approaches i.e. transient analysis and response spectrum analysis are adopted for the seismic analysis in ANSYS.

## Meshing

Meshing is used in a Workbench is to provide robust, ease in the use of meshing. These tools are highly automated and it has a moderate to high degree of user control. To carry out a finite element analysis, the model must be divided into a number of small pieces and those pieces are known as finite elements. After the model has been divided into a number of discrete parts, Finite Element Analysis can be described as a

discretization technique.

If the system we investigate is one-dimensional in nature, we may have to use line elements to represent our geometry and carry out our analysis. If the system is two-dimensional, then a 2D mesh is required. If the system is a complex and 3D representation of the continuum, then we use a 3D mesh.

## Mesh requirements

The Finite Element Method (FEM) has certain requirements on a mesh:

- The mesh must be valid, (no holes, self-intersections, or faces joined at two or more edges).
- The mesh must conform to the boundary of the domain. This is an obvious requirement, but some schemes such as a Delaunay triangulation may not satisfy this condition.
- The density of the mesh must be controllable, to allow trade-off between accuracy and solution time.
- The grid density will vary depending on local accuracy requirements, but any variations must be smooth to reduce or eliminate numerical diffusion/refraction effects.
- There are some requirements on the shape of elements. In general, the elements should as equiangular as possible in equilateral triangles & regular tetrahedral. Highly distorted elements (long, thin triangles, squashed tetrahedral) can lead to numerical stability problems caused by round-off errors. This requirement is modified for boundary layers, where highly stretched elements are desired and facilitated in the FEM formulation. The min-max-angle property is still required in this case.

Figures 1 and 2 shows the FEA Model with Meshing which includes 320 columns and 494 beams.

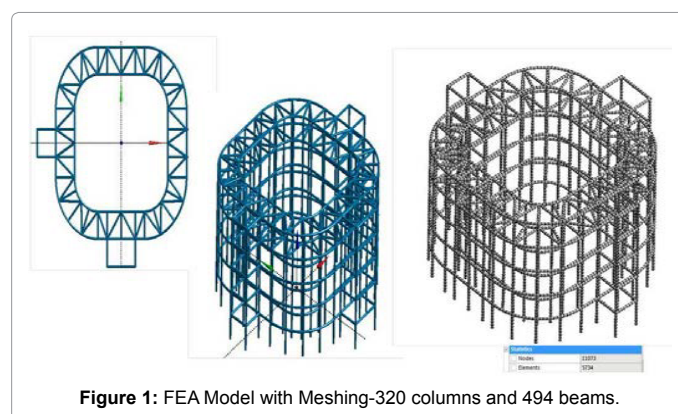


Figure 1: FEA Model with Meshing-320 columns and 494 beams.

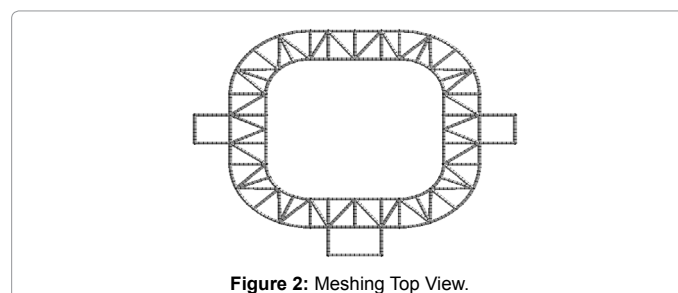


Figure 2: Meshing Top View.

## Static Structural Analysis

Static analysis calculates the effects of *steady* loading conditions on a structure. A static analysis includes *steady* inertia loads and time-varying loads that can be accounted as static equivalent loads [5]. Static analysis is used to determine the displacements, stresses, strains, and forces in structures or components. These are the kinds of loading that can be applied in a static analysis:

- Externally applied forces and pressures
- Steady-state inertial forces (gravity or rotational velocity)
- Imposed (non-zero) displacements
- Temperatures (for thermal strain)
- Fluences (for nuclear swelling)

A: Static Structural  
Fixed Support  
Time: 1. s  
■ Fixed Support

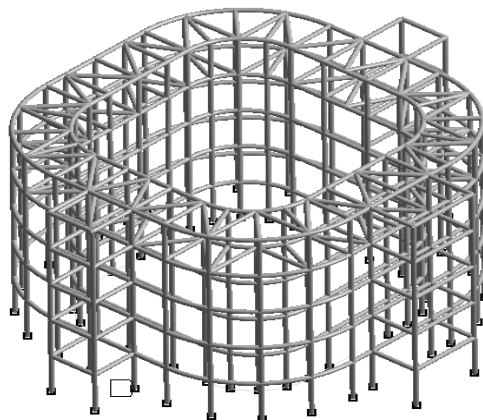
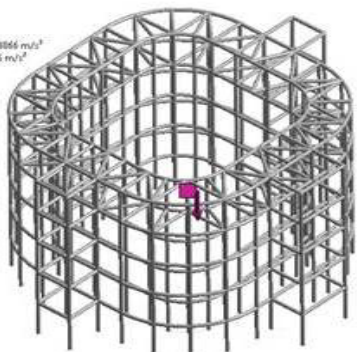


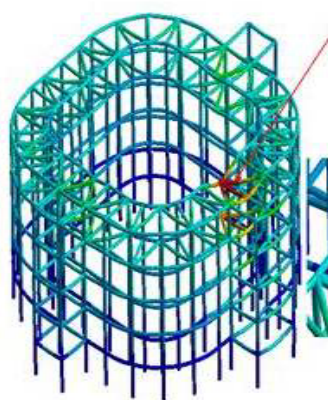
Figure 3: Fixed Support BC's.

A: Static Structural  
Standard Earth Gravity  
Time: 1. s  
■ Standard Earth Gravity: 9.8066 m/s²  
Components: 0.0, -9.8066 m/s²



A: Static Structural  
Total Deformation  
Type: Total Deformation  
Unit: mm  
Time: 1

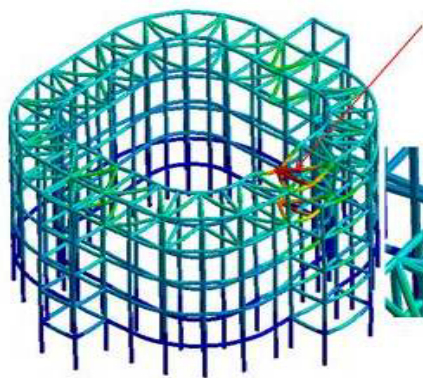
5.1909 Max  
4.6141  
4.0373  
3.4606  
2.8838  
2.307  
1.7303  
1.1535  
0.57676  
0 Min



Maximum Displacement 5mm

A: Static Structural  
Total Deformation  
Type: Total Deformation  
Unit: mm  
Time: 1

5.1909 Max  
4.6141  
4.0373  
3.4606  
2.8838  
2.307  
1.7303  
1.1535  
0.57676  
0 Min



Maximum Displacement 5mm

Figure 4: Displacement Contours.



## Overview of steps in a static analysis

The procedure for a static analysis consists of three main steps:

- Building the model.
- Applying loads and obtaining the solution.

- Reviewing the results. (Figures 3-8)

The first mode of the auditorium is rotating about an axis parallel to the x-axis in the E-W direction and the building swings in the N-S direction (Figure 9). The second and third modes are both twisting, in clockwise and counter-clockwise, respectively (Figure 9a and 9b). The

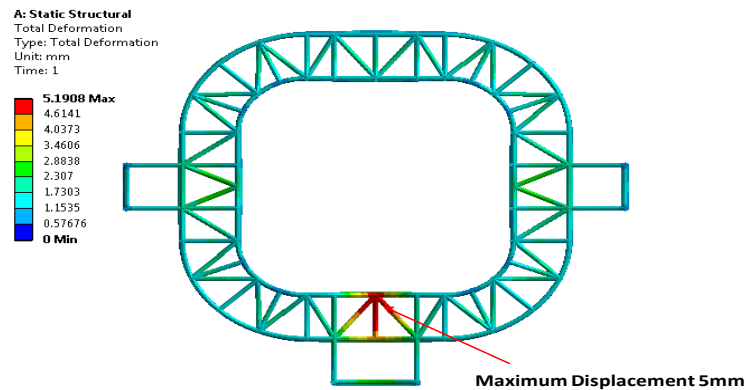


Figure 5: Displacement Contours-Top View.

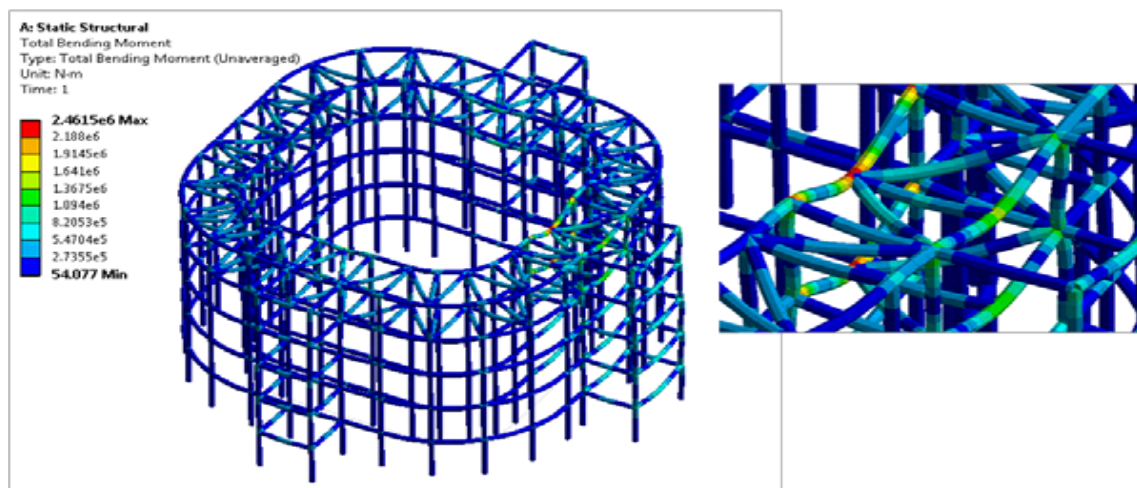


Figure 6: Total Bending Moment.

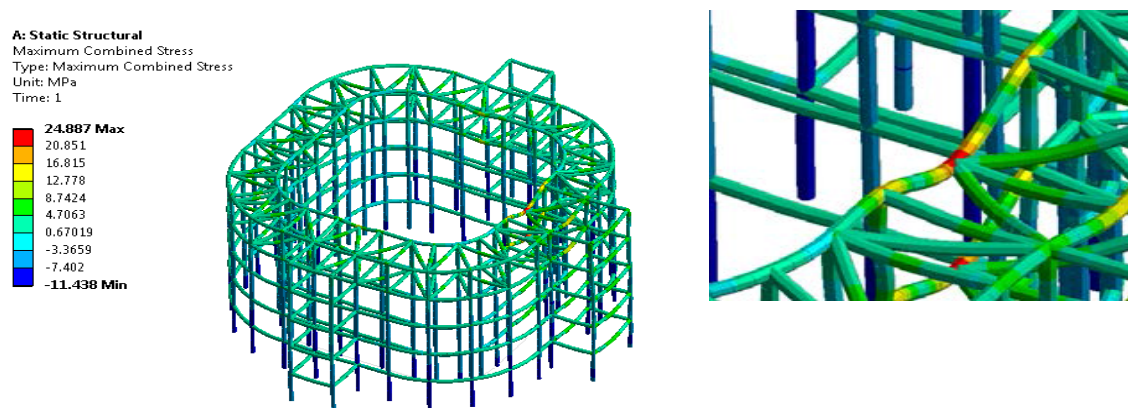


Figure 7: Maximum Combined Stress.

**A: Static Structural**  
Torsional Moment 2  
Type: Directional Torsional Moment (Unaveraged)(X Axis)  
Unit: N-m  
Solution Coordinate System  
Time: 1

**3.813e5 Max**  
2.9656e5  
2.1183e5  
1.271e5  
42366  
-42366  
-1.271e5  
-2.1183e5  
-2.9656e5  
**-3.813e5 Min**

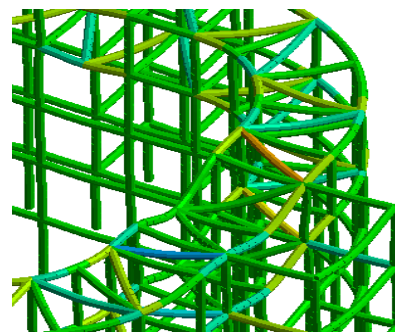
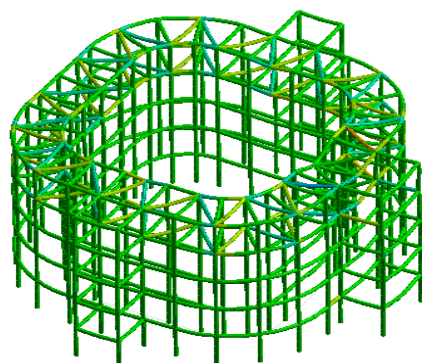


Figure 8: Torsional Moment.

**B: Modal**  
Total Deformation  
Type: Total Deformation  
Frequency: 0.76612 Hz  
Unit: m

**6.3299e-6 Max**  
5.6266e-6  
4.9233e-6  
4.2199e-6  
3.5166e-6  
2.8133e-6  
2.11e-6  
1.4066e-6  
7.0332e-7  
**0 Min**

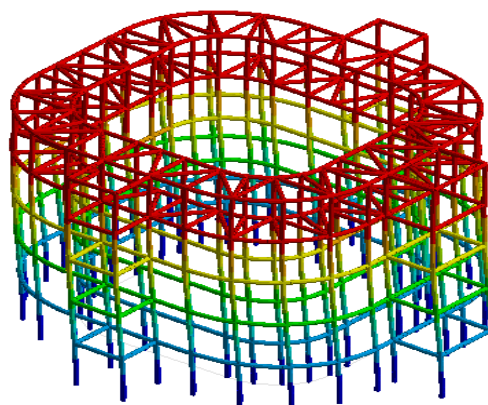


Figure 9: Natural Frequencies of Indoor Stadium: Mode-1.

**B: Modal**  
Total Deformation 2  
Type: Total Deformation  
Frequency: 0.80096 Hz  
Unit: m

**7.3779e-6 Max**  
6.5582e-6  
5.7384e-6  
4.9186e-6  
4.0989e-6  
3.2791e-6  
2.4593e-6  
1.6395e-6  
8.1977e-7  
**0 Min**

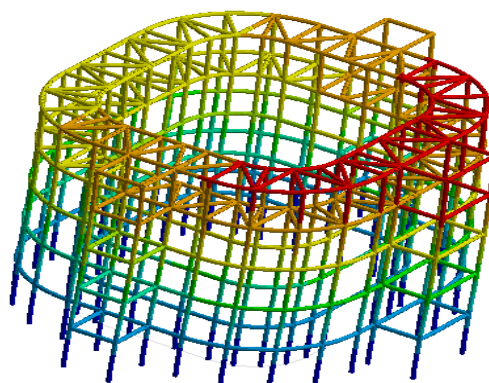


Figure 9a: Natural Frequencies of Indoor Stadium: Mode-2.

fourth mode is bending in the N-S direction (Figure 9c). The last mode shows severe vertical motion at the northwest part of the auditorium and some bending (Figure 9d).

Spectrum analysis yielded a lot of information. For the excitation, there are three displacement response values at each node: translational displacements in the x, y and z direction, rotations about the x, y and

z axis, and total displacement and rotation [6]. The same can be said about the acceleration. Therefore, a total of 3 displacement graphs can be generated. In addition, vector graphs can also be created (Figures 10-14).

## Conclusion

A 3-D finite element model was built and analyzed in the study.

**B: Modal**  
Total Deformation 3  
Type: Total Deformation  
Frequency: 0.97422 Hz  
Unit: m

8.5543e-6 Max  
7.6038e-6  
6.6533e-6  
5.7029e-6  
4.7524e-6  
3.8019e-6  
2.8514e-6  
1.901e-6  
9.5048e-7  
0 Min

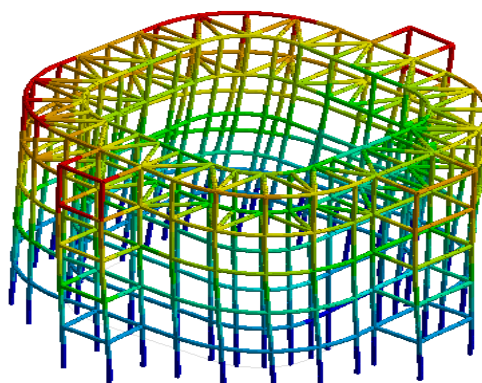


Figure 9b: Natural Frequencies of Indoor Stadium: Mode-3.

**B: Modal**  
Total Deformation 4  
Type: Total Deformation  
Frequency: 2.2202 Hz  
Unit: m

2.0446e-5 Max  
1.8174e-5  
1.5902e-5  
1.363e-5  
1.1359e-5  
9.0869e-6  
6.8152e-6  
4.5435e-6  
2.2717e-6  
0 Min

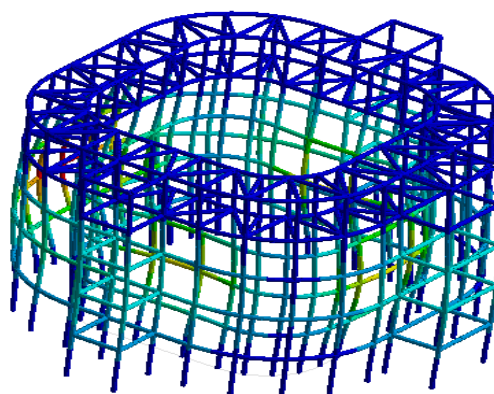


Figure 9c: Natural Frequencies of Indoor Stadium: Mode-4.

**B: Modal**  
Total Deformation 5  
Type: Total Deformation  
Frequency: 2.3373 Hz  
Unit: m

2.6548e-5 Max  
2.3598e-5  
2.0648e-5  
1.7698e-5  
1.4749e-5  
1.1799e-5  
8.8492e-6  
5.8995e-6  
2.9497e-6  
0 Min

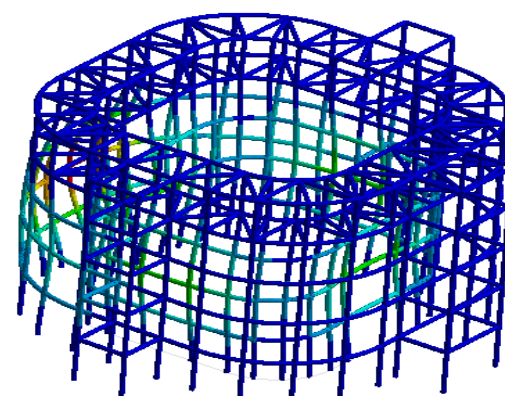


Figure 9d: Natural Frequencies of Indoor Stadium: Mode-5.

The model is based on the actual dimensions from the blueprint and includes all structural components. Static and Modal and spectrum analyses were performed with the FE package, ANSYS. The fundamental frequency obtained from the modal analysis compares well with the empirical value. Displacement, acceleration and stress distributions are generated from spectrum analysis with the response spectrum. It is suggested from the analyses that the most sensitive areas for the

accelerate meters to pick up structural motions are the top level and the northwest part of the building. .

#### Acknowledgment

My foremost gratitude goes to all that have contributed in the achievement of this study. I am Grateful to the Honourable Chancellor, **Dr. J. Sundeeep Anand**, Bharath University, Chennai.

**B: Modal**  
Total Deformation 6  
Type: Total Deformation  
Frequency: 2.3675 Hz  
Unit: m

**1.296e-5 Max**  
1.152e-5  
1.008e-5  
8.6399e-6  
7.1999e-6  
5.76e-6  
4.32e-6  
2.88e-6  
1.44e-6  
**0 Min**

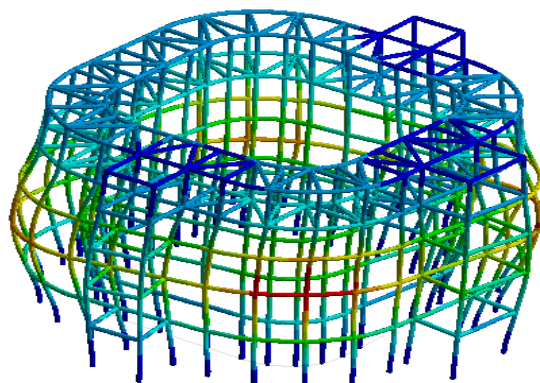


Figure 9e: Natural Frequencies of Indoor Stadium: Mode-6.

**B: Modal**  
Total Deformation 7  
Type: Total Deformation  
Frequency: 2.5087 Hz  
Unit: m

**1.9086e-5 Max**  
1.6966e-5  
1.4845e-5  
1.2724e-5  
1.0603e-5  
8.4828e-6  
6.3621e-6  
4.2414e-6  
2.1207e-6  
**0 Min**

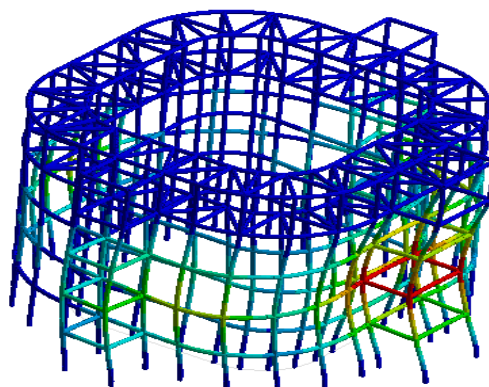


Figure 9f: Natural Frequencies of Indoor Stadium: Mode-7.

**B: Modal**  
Total Deformation 8  
Type: Total Deformation  
Frequency: 2.5553 Hz  
Unit: m

**2.9592e-5 Max**  
2.6304e-5  
2.3016e-5  
1.9728e-5  
1.644e-5  
1.3152e-5  
9.8639e-6  
6.576e-6  
3.288e-6  
**0 Min**

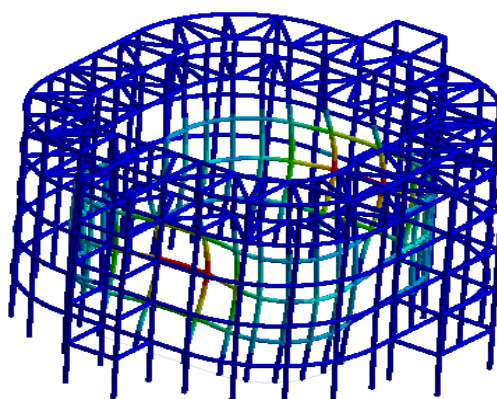


Figure 9g: Natural Frequencies of Indoor Stadium: Mode-8.

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**B: Modal**  
Total Deformation 9  
Type: Total Deformation  
Frequency: 2.5669 Hz  
Unit: m

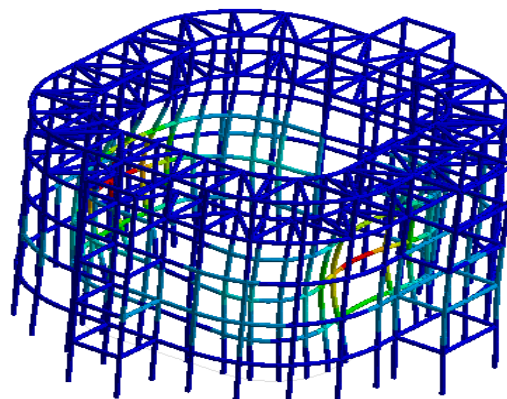
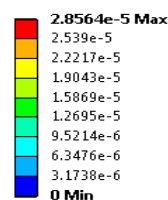


Figure 9h: Natural Frequencies of Indoor Stadium: Mode-9.

**B: Modal**  
Total Deformation 10  
Type: Total Deformation  
Frequency: 2.6134 Hz  
Unit: m

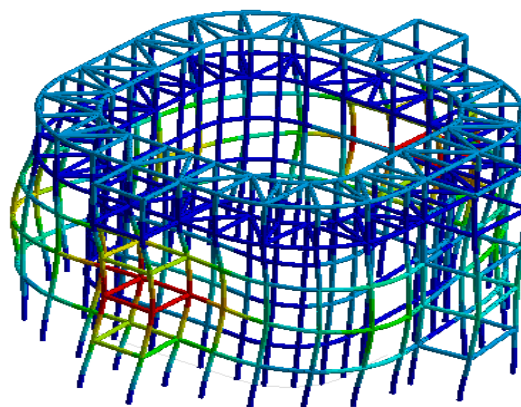
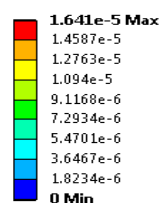


Figure 9i: Natural Frequencies of Indoor Stadium: Mode-10.

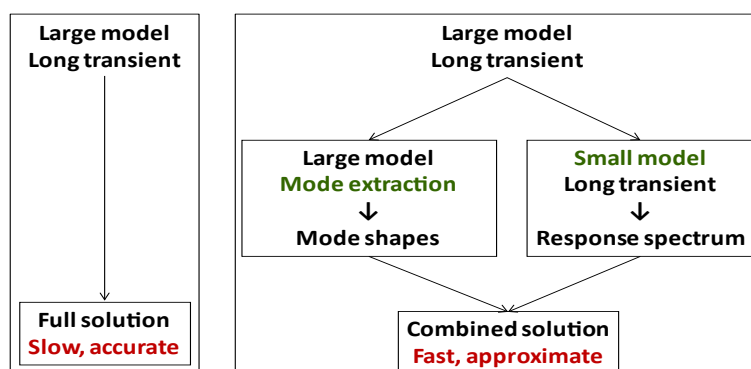


Figure 10: Response Spectrum Analysis.

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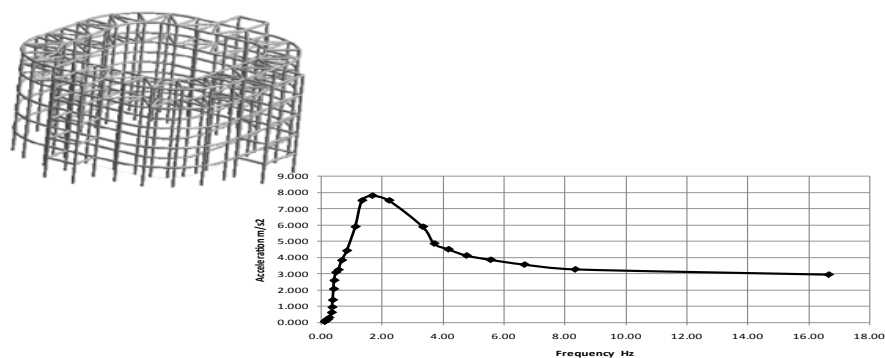


Figure 11: Seismic Load.

**C: Response Spectrum**  
 Directional Deformation 3  
 Type: Directional Deformation(Z Axis)  
 Unit: mm  
 Solution Coordinate System  
 Time: 0

**0.0039314 Max**  
 0.0034945  
 0.0030577  
 0.0026209  
 0.0021841  
 0.0017473  
 0.0013105  
 0.00087364  
 0.00043682  
**0 Min**

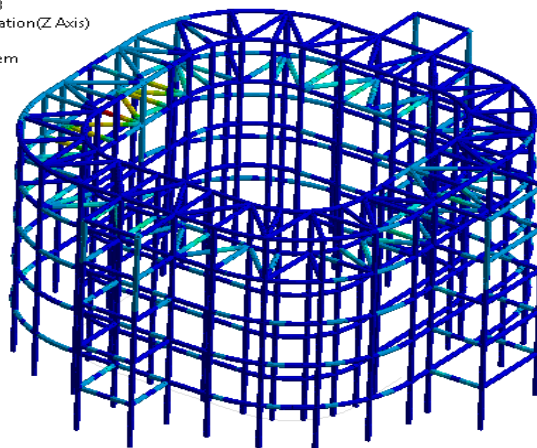


Figure 12: Deformation -X.

**C: Response Spectrum**  
 Directional Deformation 2  
 Type: Directional Deformation(Y Axis)  
 Unit: mm  
 Solution Coordinate System  
 Time: 0

**0.11184 Max**  
 0.099409  
 0.086983  
 0.074557  
 0.062131  
 0.049705  
 0.037279  
 0.024852  
 0.012426  
**0 Min**

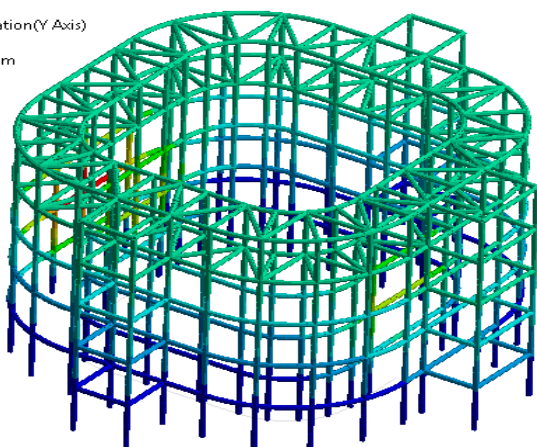
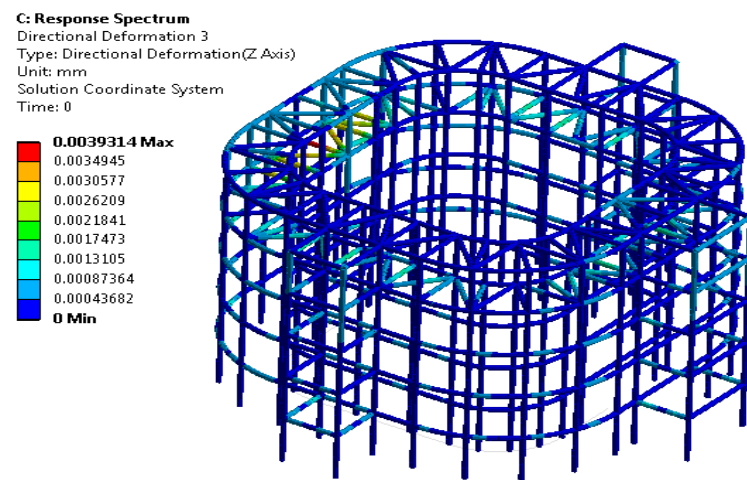


Figure 13: Deformation -Y.



**Figure 14:** Deformation –Z.