

Numerical Solution for Solving System of Fuzzy Nonlinear Integral Equation by using Modified Decomposition Method

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Abstract

In this paper, we intend to offer system of fuzzy nonlinear integral equation also numerical scheme to solve. By using the new and fast technique to solve our problem. We try to discuss some numerical aspects such as convergence and error analysis. Finally, accuracy and applicability of the proposed methods are carried out along with comparisons using some numerical examples.

Keywords: Fuzzy number; System of nonlinear fuzzy volterra integral equation; Fuzzy integral; Fuzzy remain integral; Modified decomposition method

Introduction

In recent years, Fuzzy systems are now used to study a various of problems ranging from fuzzy metric spaces [1], fuzzy topological spaces [2], to control chaotic systems [3,4], fuzzy differential equations [5-7] and particle physics [8-11]. The topics of fuzzy integral equations (FIEs) which attracted growing interest for some times, particularly, in relation to fuzzy control, have been developed. The concept of integration of fuzzy functions was firstly introduced by Dubois and Prade [12]. Alternative approaches were later suggested by the authors [13-19]. Recently, some numerical methods have been introduced to solve fuzzy integral equation. For example, Babolian et al. [20] used the Adomian decomposition method (ADM) to solve Fredholm fuzzy integral equations of the second kind (FFIEs-2). Allah Viranloo et al. [10], nonlinear integral equations. As two of the most important basic polynomials which in previous works have not been covered in fuzzy equations, modified decomposition method is proposed to solve complexity composition fuzzy kernels and complexity fuzzy nonlinear integral equation with complexly kernels, we convert a fuzzy nonlinear integral equation to a system of integral equation some numerical examples are presented to show the facts about our methods.

Preliminaries

Definition 1

Fuzzy set: A set. $\tilde{A} = \{(x, M_{\tilde{A}(x)})\}$, $x \in X$ is called a fuzzy set where $M_{\tilde{A}(x)}$ is the membership function of a fuzzy set A is defined by $M_{\tilde{A}(x)} : X \rightarrow [0,1]$, the value of $M_{\tilde{A}(x)}$ is called the membership degree x.

Definition 2

Fuzzy number: A fuzzy number is a map $\tilde{u} : R \rightarrow [a, b]$, which satisfying

- (1) \tilde{u} is upper semi-continuous function,
- (2) $\tilde{u}(x) = 0$ outside some interval $[a, d]$,
- (3) There are real numbers b, c such $a \leq b \leq c \leq d$.
 - i) $\tilde{u}(x)$ is a monotonic increasing function on $[a, b]$,
 - ii) $\tilde{u}(x)$ is a monotonic decreasing function on $[c, d]$,
 - iii) $\tilde{u}(x) = 1$ for all $x \in [b, c]$.

The set of all fuzzy numbers (as given by Definition 2) is denoted by E^1 and is a convex cone. An alternative definition for parameter from of a fuzzy number is given by Kaleva [16].

Definition 3

Fuzzy interval: Let U be a fuzzy set on R, u is called a fuzzy interval if satisfied

1. U is normal: there exist $x_0 \in R$ ST $u(x_0) = 1$.
2. U is convex: for all $x, t \in R, 0 \leq \lambda \leq 1$ it holds that $u(\lambda x + (1-\lambda)y) \geq \min\{u(x), u(y)\}$
3. U is upper semi-continuous
4. $[u] = \text{cl}\{x \in R : u(x) > 0\}$ is a compact subset of R.

Definition 4

α -Level: let E be the set of all fuzzy number on R, the α -level set of a fuzzy number $u \in E, 0 \leq \alpha \leq 1$, denoted by $[u]^\alpha$ is mapping between close interval 0,to power set of R is defined as

$$[u]^\alpha = \begin{cases} [\underline{u}(\alpha), \bar{u}(\alpha)], & \alpha \in (0, 1] \\ \text{cl}(\text{supp}), & \alpha = 0 \end{cases}$$

The α -level set of a fuzzy number is closed and bounded interval $[\underline{u}(\alpha), \bar{u}(\alpha)]$, where $\underline{u}(\alpha)$ denotes the left-hand endpoint of $[u]^\alpha$ and $\bar{u}(\alpha)$ denotes the right – hand endpoint of $[u]^\alpha$ since each $y \in R$ can be regarded as a fuzzy number \tilde{y} defined by $\tilde{y}(t) = \begin{cases} 1 & \text{if } t = y \\ 0 & \text{if } t \neq y \end{cases}$.

Definition 5

A fuzzy number \tilde{u} in parametric form is a pair (\underline{u}, \bar{u}) of function $\underline{u}(\alpha), \bar{u}(\alpha), 0 \leq \alpha \leq 1$, which satisfies the following requiremenst:

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- i) $\underline{u}(\alpha)$ is a bounded left continuous non-decreasing function over $[0, 1]$
- ii) $\bar{U}(\alpha)$ is a bounded left continuous non-increasing function over $[0, 1]$
- iii) $\underline{u}(\alpha) \leq \bar{u}(\alpha), 0 \leq \alpha \leq 1$.

Definition 6

For arbitrary fuzzy $u = (\underline{u}(\alpha), \bar{u}(\alpha), v = (\underline{v}(\alpha), \bar{v}(\alpha), 0 \leq \alpha \leq 1$ and scalar k , we define addition, subtraction, scalar product by k and multiplication are respectively as following:

1. Addition: $(u + v)\alpha = (\underline{u}(\alpha) + \underline{v}(\alpha), \bar{u}(\alpha) + \bar{v}(\alpha))$
 2. Subtraction: $(u - v)\alpha = (\underline{u}(\alpha) - \underline{v}(\alpha), \bar{u}(\alpha) - \bar{v}(\alpha))$
 3. Scalar product: $k \underline{u} = \begin{cases} (k\underline{u}(\alpha), k\bar{u}(\alpha)), & k \geq 0 \\ (k\underline{u}(\alpha), k\bar{u}(\alpha)), & k < 0 \end{cases}$ (1)
 4. Multiplication:
- $$\underline{\bar{u}} \cdot \bar{v} = \begin{cases} \underline{u}\bar{v}(\alpha) = \max\{\underline{u}(\alpha)\underline{v}(\alpha), \underline{u}(\alpha)\bar{v}(\alpha), \bar{u}(\alpha)\underline{v}(\alpha), \bar{u}(\alpha)\bar{v}(\alpha)\} \\ \bar{u}\bar{v}(\alpha) = \min\{\underline{u}(\alpha)\underline{v}(\alpha), \underline{u}(\alpha)\bar{v}(\alpha), \bar{u}(\alpha)\underline{v}(\alpha), \bar{u}(\alpha)\bar{v}(\alpha)\} \end{cases} . \quad (2)$$

Definition 7

For arbitrary Fuzzy numbers $\tilde{u}, \tilde{v} \in E^1$, we use the distance

$$D(\tilde{u}, \tilde{v}) = \max \left\{ \sup_{\alpha \in [0,1]} |\underline{u}(\alpha) - \underline{v}(\alpha)|, \sup_{\alpha \in [0,1]} |\bar{u}(\alpha) - \bar{v}(\alpha)| \right\} \quad (3)$$

And it is show fuzzy interval that (E^1, D) is a complete metric space.

Definition 8

Let $\tilde{f}(x)$ be a close and bounded fuzzy value function on $[a,b]$. Suppose the $\tilde{f}_\alpha^L(x)$ and $\tilde{f}_\alpha^R(x)$ are a Riemann - integral on $[a,b]$ for all $\alpha \in [0,1]$ in fuzzy number.

Let

$$A_a = \left[\int_a^b \tilde{f}_\alpha^L(x) dx, \int_a^b \tilde{f}_\alpha^R(x) dx \right]$$

Then we say that $\tilde{f}(x)$ is fuzzy - Riemann - integral of $[a,b]$ and the membership function of $\int_a^b \tilde{f}(x) dx$ is defined by

$$M_{\int_a^b \tilde{f}(x) dx}(\alpha) = \sup_{0 \leq \alpha \leq 1} \alpha \cdot 1_{A_\alpha}(r) \quad \text{for } r \in A_0.$$

Definition 9

The integral of a fuzzy function was define in [16] by using the Riemann integral concept. Let $f: [a,b] \rightarrow E^1$. For Fuzzy function, for each partition $P = \{t_0, \dots, t_n\}$ of $[a,b]$ and for arbitrary $i \in [t_{i-1}, t_i], 1 \leq i \leq n$, suppose

$$R_P = \sum_{i=1}^n f(t_i)(t_i - t_{i-1}) \quad (4)$$

$$\Delta := \max \{ |t_i - t_{i-1}|, 1 \leq i \leq n \}$$

The define integral of $f(t)$ over $[a,b]$ is

$$\int_a^b f(t) dt = \lim_{\Delta \rightarrow 0} R_P \quad (5)$$

If the fuzzy function $f(t)$ is continuous in metric D its definite the integral exists and also

$$\left(\int_a^b f(t; \alpha) dt \right) = \int_a^b f(t; \alpha) dt, \left(\int_a^b f(t; \alpha) dt \right) = \left(\int_a^b f(t; \alpha) dt \right) \quad (6)$$

It should be noted that the fuzzy integral can be also defined using the Lebesgue - type approach. However, if $f(t)$ is continuous, both approaches yield the same value. More details about the properties of the fuzzy integral.

Definition 10

Let $F: I \rightarrow E^n$ the integral of F over, denoted by $\int_I^b F(x) dx$ or $\int_a^b F(x) dx$, is defined level wise by

$$\left[\int_I^a F(x) dx \right]^a = \int_I^b F(x)_a dx = \left\{ \int_I^b f(x) dx \mid f: I \rightarrow R^n \text{ is a measurable} \right.$$

function $F(x)_a$ for all $0 \leq \alpha \leq 1$.

Proposition

A function $F: G \rightarrow E^n$ be integrable and $\phi \in R$ then

$$1. \int(F+G) = \int F + \int G$$

$$2. 2 \cdot \int \phi F = \int F$$

$$3. 3\text{-D}(F, G) \text{ is integrable}$$

$$4. 4\text{-D}(\int F, \int G) \leq D(F, G).$$

Theorem

For any $p, q, r, s \in E^n$ and $\phi \in R$, then the following hold

$$I. (E^n, D) \text{ is a complete metric space}$$

$$II. D(\phi p, \phi q) = |\phi| D(p, q)$$

$$III. D(p+r, q+s) = D(p, q)$$

$$IV. D(p+q, r+s) \leq D(p+q, r+s) \leq (p+r) + D(q, s).$$

Fuzzy System of Nonlinear Volterra Integral Equation

The fuzzy system of nonlinear integral equation with integral kernel which is discussed in this work is the fuzzy system of nonlinear Volterra integral equation as follows:

$$\begin{aligned} \widetilde{u}_1(x) &= \tilde{f}_1(x) + \sum_{j=1}^m \lambda_{1j} \int_a^x k_{1j}(x, t, \tilde{G}_{1j}(t, \tilde{F}(t, \tilde{u}_j(t)))) dt \\ &\vdots \\ \widetilde{u}_i(x) &= \tilde{f}_i(x) + \sum_{j=1}^m \lambda_{ij} \int_a^x k_{ij}(x, t, \tilde{G}_{ij}(t, \tilde{F}(t, \tilde{u}_j(t)))) dt \\ &\vdots \\ \widetilde{u}_m(x) &= \tilde{f}_m(x) + \sum_{j=1}^m \lambda_{mj} \int_a^x k_{mj}(x, t, \tilde{G}_{mj}(t, \tilde{F}(t, \tilde{u}_j(t)))) dt. \end{aligned} \quad (7)$$

Where $\lambda_{ij} > 0$ (for $i, j = 1, \dots, m$), $\tilde{f}_i(x)$ is a fuzzy function of x such that $x, t \in [a, b]$, also $k_{ij}(x, t, \tilde{G}_{ij}(t, \tilde{F}(t, \tilde{u}_j(t)))): I \times E^1 \rightarrow E^1$ is analytic functions, $\tilde{F}(t, \tilde{u}_j(t)): I \times E^1 \rightarrow E^1$ is fuzzy continuous functions, consider the pairs $\tilde{f}_i(x) = \underline{f}_i(x, \alpha), \bar{f}_i(x, \alpha)$ and $\tilde{u}_i(t) = \underline{u}_i(t, \alpha), \bar{u}_i(t, \alpha), 0 \leq \alpha \leq 1$ and $x \in I = [a, b]$, is solution will be determined. Then, the parametric frm of eqn. (2) is given fuzzy integral equations system as follows.

$$\begin{aligned} \underline{u}_m(x, \alpha) &= \\ \underline{f}_m(x, \alpha) & \\ + \sum_{j=1}^m \bar{e}_{mj} \int_a^x k_{mj}(x, t, G_{mj}(t, F(t, u_{jm}(t, \alpha)))) dt & \\ \bar{u}_m(x, \alpha) &= \\ \bar{f}_m(x, \alpha) &+ \\ \sum_{j=1}^m \bar{e}_{mj} \int_a^x k_{mj}(x, t, G_{mj}(t, F(t, u_{jm}(t, \alpha)))) dt & . \end{aligned} \quad (8)$$

We can see that eqn. (1) convert to a system of nonlinear Volterra integral equations in crisp case in eqn. (7). We have:

$$\begin{aligned} \underline{u}_m(x, \alpha) &= \\ \underline{f}_m(x, \alpha) &+ \\ \sum_{j=1}^m \lambda_{mj} \int_a^c k_{mj}(x, t, G_{mj}(t, F(t, u_{jm}(t, \alpha)))) dt &+ \\ \sum_{j=1}^m \lambda_{mj} \int_c^x k_{mj}(x, t, G_{mj}(t, F(t, u_{jm}(t, \alpha)))) dt & \\ \bar{u}_m(x, \alpha) &= \bar{f}_m(x, \alpha) \\ + \sum_{j=1}^m \lambda_{mj} \int_a^c k_{mj}(x, t, G_{mj}(t, F(t, u_{jm}(t, \alpha)))) dt &+ \\ \sum_{j=1}^m \lambda_{mj} \int_c^x k_{mj}(x, t, G_{mj}(t, F(t, u_{jm}(t, \alpha)))) dt & . \end{aligned}$$

Where $0 \leq t \leq c$, $c \leq t \leq x$, $0 \leq \alpha \leq 1$. Now we will find the parameter for the eqn. (8), as follows

$$\begin{aligned} k_{mj}(x, t, G_{mj}(t, F(t, u_{jm}(t, \alpha)))) &= \\ \left\{ \begin{array}{l} k_{mj}(x, t, G_{mj}(t, F(t, u_{jm}(t, \alpha)))), k_{mj}(x, t, G_{mj}(t, F(t, u_{jm}(t, \alpha)))) \geq 0 \\ k_{mj}(x, t, G_{mj}(t, F(t, u_{jm}(t, \alpha)))), k_{mj}(x, t, G_{mj}(t, F(t, u_{jm}(t, \alpha)))) < 0 \end{array} \right. \\ G_{mj}(t, F(t, u_{jm}(t, \alpha))) &= \left\{ \begin{array}{l} G_{mj}(t, F(t, u_{jm}(t, \alpha))), G_{mj}(t, F(t, u_{jm}(t, \alpha))) \geq 0 \\ G_{mj}(t, F(t, u_{jm}(t, \alpha))), G_{mj}(t, F(t, u_{jm}(t, \alpha))) < 0 \end{array} \right. \\ \frac{G_{mj}(t, F(t, u_{jm}(t, \alpha)))}{G_{mj}(t, F(t, u_{jm}(t, \alpha)))} &= \left\{ \begin{array}{l} \bar{G}_{mj}(t, \bar{F}(t, \bar{u}_{jm}(t, \alpha))), \bar{G}_{mj}(t, \bar{F}(t, \bar{u}_{jm}(t, \alpha))) \geq 0 \\ \bar{G}_{mj}(t, \bar{F}(t, \bar{u}_{jm}(t, \alpha))), \bar{G}_{mj}(t, \bar{F}(t, \bar{u}_{jm}(t, \alpha))) < 0 \end{array} \right. \\ k_{mj}(x, t, G_{mj}(t, F(t, u_{jm}(t, \alpha)))) &= \left\{ \begin{array}{l} k_{mj}(x, t, G_{mj}(t, F(t, u_{jm}(t, \alpha)))), k_{mj}(x, t, G_{mj}(t, F(t, u_{jm}(t, \alpha)))) \geq 0 \\ k_{mj}(x, t, G_{mj}(t, F(t, u_{jm}(t, \alpha)))), k_{mj}(x, t, G_{mj}(t, F(t, u_{jm}(t, \alpha)))) < 0 \end{array} \right. \\ G_{mj}(t, F(t, u_{jm}(t, \alpha))) &= \left\{ \begin{array}{l} \bar{G}_{mj}(t, \bar{F}(t, \bar{u}_{jm}(t, \alpha))), \bar{G}_{mj}(t, \bar{F}(t, \bar{u}_{jm}(t, \alpha))) \geq 0 \\ \bar{G}_{mj}(t, \bar{F}(t, \bar{u}_{jm}(t, \alpha))), \bar{G}_{mj}(t, \bar{F}(t, \bar{u}_{jm}(t, \alpha))) < 0 \end{array} \right. \\ G_{mj}(t, F(t, u_{jm}(t, \alpha))) &= \left\{ \begin{array}{l} G_{mj}(t, F(t, u_{jm}(t, \alpha))), G_{mj}(t, F(t, u_{jm}(t, \alpha))) \geq 0 \\ G_{mj}(t, F(t, u_{jm}(t, \alpha))), G_{mj}(t, F(t, u_{jm}(t, \alpha))) < 0 \end{array} \right. \end{aligned} \quad (9)$$

Where $j=1, \dots, m$

than

$$\begin{aligned} \underline{u}_m(x, \alpha) &= \underline{f}_m(x, \alpha) \\ + \sum_{j=1}^m \left[\int_a^d k_{mj}(x, t, G_{mj}(t, F(t, \underline{u}_{jm}(t, \alpha)))) dt \right. & \\ + \int_d^c k_{mj}(x, t, \bar{G}_{mj}(t, \bar{F}(t, \bar{u}_{jm}(t, \alpha)))) dt + & \\ \left. \int_c^e k_{mj}(x, t, G_{mj}(t, F(t, \bar{u}_{jm}(t, \alpha)))) dt \right] & \\ \bar{u}_m(x, \alpha) &= \bar{f}_m(x, \alpha) \\ + \sum_{j=1}^m \left[\int_a^d k_{mj}(x, t, \bar{G}_{mj}(t, \bar{F}(t, \bar{u}_{jm}(t, \alpha)))) dt \right. & \\ + \int_d^c k_{mj}(x, t, k(x, t, G_{mj}(t, F(t, \bar{u}_{jm}(t, \alpha))))) dt + & \\ \left. \int_c^e k_{mj}(x, t, \bar{G}_{mj}(t, \bar{F}(t, \bar{u}_{jm}(t, \alpha)))) dt \right] & \\ \end{aligned} \quad (10)$$

where $0 \leq t \leq d$, $d \leq t \leq c$, $c \leq t \leq e$, $e \leq t \leq x$, $0 \leq \alpha \leq 1$.

This is the condition for the fuzzy nonlinear integral system. If $i=n$ that mean we will reply eqns. (6) and (7) for all time n , for example if $i=2$ is mean we have two equations in fuzzy type and the parametric from eqn. (10) from $\tilde{f}_m(x) = (\underline{f}_m(x, \alpha), \bar{f}_m(x, \alpha))$ and $\tilde{u}_m(x) = (\underline{u}_m(x, \alpha), \bar{u}_m(x, \alpha))$ respectively.

The eqn. (6) is convert to the system of nonlinear volterra integral equations in crisp case. Now we will explain modified decomposition method to solve our system and find the approximate solution for $\tilde{u}(x)$ $a \leq x \leq b$.

Modified Decomposition Method

The Adomian asserts that the decomposition method provides an efficient and computationally convenient method for generating approximate series solution to a widely class of equations. The method is applied as follows:

Standard Adomian method define the solution $\underline{u}(x, \alpha)$ $\bar{u}(x, \alpha)$ the series

$$\begin{cases} \underline{u}(x, \alpha) = \sum_{i=0}^{\infty} \underline{u}_i(x, \alpha) \\ \bar{u}(x, \alpha) = \sum_{i=0}^{\infty} \bar{u}_i(x, \alpha) \end{cases} \quad (11)$$

$$0 \leq \alpha \leq 1$$

Substitution the series decomposition [11] into both side of eqn. (7) and assuming that the function $\underline{f}_i, \bar{f}_i$ can be expressed as the sum of two part $\underline{f}_{i0}, \bar{f}_{i0}, \underline{f}_{il}, \bar{f}_{il}$, therefore used

$$\begin{cases} \underline{f}_i = \underline{f}_{i0} + \underline{f}_{il} \\ \bar{f}_i = \bar{f}_{i0} + \bar{f}_{il} \end{cases}, i=1, 2, 3, \dots, m \quad (12)$$

In view of the assumption, we propose a slight variation is that only the part $\underline{f}_{i0}, \bar{f}_{i0}$ is assigned to the zeroth component $\underline{u}_{i0}, \bar{u}_{i0}$ and

the remaining part $\underline{f}_{i0} \bar{f}_{il}$ are combined with the others terms (integral part) to define $\underline{u}_{i0r}, \bar{u}_{i0r}$, based on the suggestion formulate the following modified decomposition methods ,rewrite eqn. (9). We get

$$\begin{aligned} \sum_{i=0}^{\infty} \underline{u}_{im}(x, \alpha) &= \\ &\underline{f}_{i0}(x, \alpha) + \bar{f}_{il}(x, \alpha) \\ &+ \sum_{j=1}^m \left[\int_a^d \underline{k}_{mj}(x, t, \underline{G}_{mj}) \left(t, \underline{F} \left(t, [R \sum_{i=0}^{\infty} \underline{u}_{jm-1i}(t, \alpha) + N \sum_{i=0}^{\infty} \bar{u}_{jm-1i}(t, \alpha)] \right) \right) dt \right. \\ &\quad \left. + \int_d^c \underline{k}_{mj}(x, t, \bar{G}_{mj}) \left(t, \bar{F} \left(t, [R \sum_{i=0}^{\infty} \bar{u}_{jm-1i}(t, \alpha) + N \sum_{i=0}^{\infty} \underline{u}_{jm-1i}(t, \alpha)] \right) \right) dt \right] \\ &dt + \\ &\int_c^e \underline{k}_{mj}(x, t, \underline{G}_{mj}) \left(t, \underline{F} \left(t, [R \sum_{i=0}^{\infty} \bar{u}_{jm-1i}(t, \alpha) + N \sum_{i=0}^{\infty} \underline{u}_{jm-1i}(t, \alpha)] \right) \right) dt + \\ &\int_e^x \underline{k}_{mj}(x, t, \bar{G}_{mj}) \left(t, \bar{F} \left(t, [R \sum_{i=0}^{\infty} \underline{u}_{jm-1i}(t, \alpha) + N \sum_{i=0}^{\infty} \bar{u}_{jm-1i}(t, \alpha)] \right) \right) dt \\ \sum_{i=0}^{\infty} \bar{u}_{im}(x, \alpha) &= \\ &\bar{f}_{i0}(x, \alpha) + \bar{f}_{il}(x, \alpha) \\ &+ \sum_{j=1}^m \left[\int_a^d \underline{k}_{mj}(x, t, \bar{G}_{mj}) \left(t, \bar{F} \left(t, [R \sum_{i=0}^{\infty} \bar{u}_{jm-1i}(t, \alpha) + N \sum_{i=0}^{\infty} \underline{u}_{jm-1i}(t, \alpha)] \right) \right) dt \right. \\ &\quad \left. + \int_d^c \underline{k}_{mj}(x, t, \underline{G}_{mj}) \left(t, \underline{F} \left(t, [R \sum_{i=0}^{\infty} \underline{u}_{jm-1i}(t, \alpha) + N \sum_{i=0}^{\infty} \bar{u}_{jm-1i}(t, \alpha)] \right) \right) dt \right. \\ &\quad \left. + \int_c^e \underline{k}_{mj}(x, t, \bar{G}_{mj}) \left(t, \bar{F} \left(t, [R \sum_{i=0}^{\infty} \underline{u}_{jm-1i}(t, \alpha) + N \sum_{i=0}^{\infty} \bar{u}_{jm-1i}(t, \alpha)] \right) \right) dt \right. \\ &\quad \left. + \int_e^x \underline{k}_{mj}(x, t, \underline{G}_{mj}) \left(t, \underline{F} \left(t, [R \sum_{i=0}^{\infty} \bar{u}_{jm-1i}(t, \alpha) + N \sum_{i=0}^{\infty} \underline{u}_{jm-1i}(t, \alpha)] \right) \right) dt \right] \end{aligned}$$

Where $0 \leq t \leq d$, $d \leq t \leq c$, $c \leq t \leq e$, $e \leq t \leq x, 0 \leq \alpha \leq 1$

The Modified decomposition method introduces the use of the recurrence relation

$$\begin{aligned} \underline{u}_{0m}(x, \alpha) &= \underline{f}_{00}(x, \alpha) \\ \underline{u}_{1m}(x, \alpha) &= \underline{f}_{11}(x, \alpha) \\ &+ \sum_{j=1}^m \left[\int_a^d \underline{k}_{mj}(x, t, \underline{G}_{mj}) \left(t, \underline{F} \left(t, [R \sum_{i=0}^{\infty} \underline{u}_{j(m-1)0}(t, \alpha) + N \sum_{i=0}^{\infty} \bar{u}_{j(m-1)0}(t, \alpha)] \right) \right) dt + \right. \\ &\quad \left. \int_d^c \underline{k}_{12y}(x, t, \bar{G}_2) \left(t, \bar{F} \left(t, [R \sum_{r=0}^{\infty} \bar{u}_{2(n-1)0}(t, \alpha) + N \sum_{r=0}^{\infty} \underline{u}_{2(n-1)0}(t, \alpha)] \right) \right) dt + \right. \\ &\quad \left. \int_c^e \underline{k}_{21}(x, t, \underline{G}_1) \left(t, \bar{F} \left(t, [R \sum_{r=0}^{\infty} \bar{u}_{1(n-1)r}(t, \alpha) + N \sum_{r=0}^{\infty} \underline{u}_{1(n-1)r}(t, \alpha)] \right) \right) dt \right. \\ &\quad \left. + \int_e^x \underline{k}_{22}(x, t, \bar{G}_2) \left(t, \bar{F} \left(t, [R \sum_{r=0}^{\infty} \underline{u}_{2(n-1)0}(t, \alpha) + N \sum_{r=0}^{\infty} \bar{u}_{2(n-1)0}(t, \alpha)] \right) \right) dt \right] \\ \underline{u}_{n(r+2)}(x, \alpha) &= \int_a^d \underline{k}_{11}(x, t, \underline{G}_1) \left(t, \underline{F} \left(t, [R \sum_{r=0}^{\infty} \underline{u}_{1(n-1)r}(t, \alpha) + N \sum_{r=0}^{\infty} \bar{u}_{1(n-1)r}(t, \alpha)] \right) \right) dt + \\ &\quad \int_d^c \underline{k}_{12}(x, t, \bar{G}_2) \left(t, \bar{F} \left(t, [\bar{u}_{2n-1}(t, \alpha)] \right) \right) dt = (x-t)t(\bar{u}_{2n-1}(t, \alpha))^2 \\ &\quad \int_c^e \underline{k}_{21}(x, t, \underline{G}_1) \left(t, \bar{F} \left(t, [\bar{u}_{2n-1}(t, \alpha)] \right) \right) dt = x^2t(\bar{u}_{2n-1}(t, \alpha))^2 \\ &\quad \int_e^x \underline{k}_{22}(x, t, \bar{G}_2) \left(t, \bar{F} \left(t, [\bar{u}_{2n-1}(t, \alpha)] \right) \right) dt = t^5(\bar{u}_{2n-1}(t, \alpha))^2 \\ &\quad \underline{f}_{i0}(x, \alpha) = x\alpha - \left(\frac{x^9}{72} + 0.00625 \right) \alpha^2 - x(0.000217(2-\alpha)^2 - 0.00074\alpha - 0.000217) \\ &\quad + (2-\alpha)^2 \left(0.0000977 - \frac{x^4}{4} + 0.0156 \right) \\ \bar{f}_{i0}(x, \alpha) &= x(2-\alpha) - \alpha^2(0.0156 + 0.000977 - \frac{x^{10}}{90}) - x(0.00049(2-\alpha)^2 + \alpha^2) \\ &\quad + (2-\alpha)^2 \left(0.000217 - \frac{x^5}{5} + 0.00625 \right) \\ \bar{f}_{00}(x, \alpha) &= x^2(2-\alpha) - 0.00625x\alpha^2 - (2-\alpha)^2 \left(0.000044 + \frac{x^6}{4} - 0.0156x^2 + \frac{x^{10}}{10} - 0.000977 \right) \end{aligned} \tag{13}$$

$$\begin{aligned} \bar{u}_{i0r}(x, \alpha) &= \underline{f}_{i1}(x, \alpha) + \int_a^d \underline{k}_{12y}(x, t, \bar{G}_2) \left(t, \bar{F} \left(t, [R \sum_{r=0}^{\infty} \bar{u}_{2(n-1)r}(t, \alpha) + N \sum_{r=0}^{\infty} \underline{u}_{2(n-1)r}(t, \alpha)] \right) \right) dt + \\ &\quad \int_d^c \underline{k}_{11}(x, t, \underline{G}_1) \left(t, \underline{F} \left(t, [R \sum_{r=0}^{\infty} \underline{u}_{1(n-1)r}(t, \alpha) + N \sum_{r=0}^{\infty} \bar{u}_{1(n-1)r}(t, \alpha)] \right) \right) dt + \\ &\quad \int_c^e \underline{k}_{22}(x, t, \bar{G}_2) \left(t, \bar{F} \left(t, [R \sum_{r=0}^{\infty} \underline{u}_{2(n-1)r}(t, \alpha) + N \sum_{r=0}^{\infty} \bar{u}_{2(n-1)r}(t, \alpha)] \right) \right) dt + \\ &\quad \int_e^x \underline{k}_{21}(x, t, \underline{G}_1) \left(t, \underline{F} \left(t, [R \sum_{r=0}^{\infty} \bar{u}_{1(n-1)r}(t, \alpha) + N \sum_{r=0}^{\infty} \underline{u}_{1(n-1)r}(t, \alpha)] \right) \right) dt \\ \bar{u}_{1n(r+2)}(x, \alpha) &= \int_a^d \underline{k}_{12}(x, t, \bar{G}_2) \left(t, \bar{F} \left(t, [R \sum_{r=0}^{\infty} \bar{u}_{2(n-1)r}(t, \alpha) + N \sum_{r=0}^{\infty} \underline{u}_{2(n-1)r}(t, \alpha)] \right) \right) dt + \\ &\quad \int_d^c \underline{k}_{21}(x, t, \underline{G}_1) \left(t, \underline{F} \left(t, [R \sum_{r=0}^{\infty} \bar{u}_{1(n-1)r}(t, \alpha) + N \sum_{r=0}^{\infty} \underline{u}_{1(n-1)r}(t, \alpha)] \right) \right) dt + \\ &\quad \int_c^e \underline{k}_{22}(x, t, \bar{G}_2) \left(t, \bar{F} \left(t, [R \sum_{r=0}^{\infty} \underline{u}_{2(n-1)r}(t, \alpha) + N \sum_{r=0}^{\infty} \bar{u}_{2(n-1)r}(t, \alpha)] \right) \right) dt + \\ &\quad \int_e^x \underline{k}_{11}(x, t, \underline{G}_1) \left(t, \underline{F} \left(t, [R \sum_{r=0}^{\infty} \bar{u}_{1(n-1)r}(t, \alpha) + N \sum_{r=0}^{\infty} \underline{u}_{1(n-1)r}(t, \alpha)] \right) \right) dt \\ &\quad + \int_a^d \underline{k}_{12}(x, t, \bar{G}_2) \left(t, \bar{F} \left(t, [\bar{u}_{2n-1}(t, \alpha)] \right) \right) dt = (x-t)t(\bar{u}_{2n-1}(t, \alpha))^2 \\ &\quad + \int_d^c \underline{k}_{21}(x, t, \underline{G}_1) \left(t, \underline{F} \left(t, [\bar{u}_{2n-1}(t, \alpha)] \right) \right) dt = x^2t(\bar{u}_{2n-1}(t, \alpha))^2 \\ &\quad + \int_c^e \underline{k}_{22}(x, t, \bar{G}_2) \left(t, \bar{F} \left(t, [\bar{u}_{2n-1}(t, \alpha)] \right) \right) dt = t^5(\bar{u}_{2n-1}(t, \alpha))^2 \\ &\quad \bar{f}_{i1}(x, \alpha) = x\alpha - \left(\frac{x^9}{72} + 0.00625 \right) \alpha^2 - x(0.000217(2-\alpha)^2 - 0.00074\alpha - 0.000217) \\ &\quad + (2-\alpha)^2 \left(0.0000977 - \frac{x^4}{4} + 0.0156 \right) \\ \bar{f}_{01}(x, \alpha) &= x(2-\alpha) - \alpha^2(0.0156 + 0.000977 - \frac{x^{10}}{90}) - x(0.00049(2-\alpha)^2 + \alpha^2) \\ &\quad + (2-\alpha)^2 \left(0.000217 - \frac{x^5}{5} + 0.00625 \right) \\ \bar{f}_{00}(x, \alpha) &= x^2(2-\alpha) - 0.00625x\alpha^2 - (2-\alpha)^2 \left(0.000044 + \frac{x^6}{4} - 0.0156x^2 + \frac{x^{10}}{10} - 0.000977 \right) \\ k \geq 0 . \end{aligned}$$

As started before, we many need only two iteration to derive the exact solution. If more than two iteration are needed $\left[N(\underline{u}_{j(n-1)r+1}(t, \alpha), N(\bar{u}_{j(n-1)r+1}(t, \alpha)) \right]$ should be represented by Adomian polynomial which can easily be generated for all types of non-linearity.

The choice of $\underline{f}_{i0}(x, \alpha), \bar{f}_{i0}(x, \alpha)$ cantina the minimal number of terms has a strong influence on facilitating the recurrence relation, and as a consequence, accelerates the convergence of the solution. Also the exact selution must be a term of $\underline{f}_i(x, \alpha), \bar{f}_i(x, \alpha)$ or to be a part of series of $\underline{f}_i(x, \alpha), \bar{f}_i(x, \alpha)$. This means that the success of this method depends mainly on the proper choice of $\underline{f}_{i0}, \bar{f}_{i0}$ and $\underline{f}_{il}, \bar{f}_{il}$. We have been unable to establish any criteria to judge what forms $\underline{f}_{i0}, \bar{f}_{i0}$ and $\underline{f}_{il}, \bar{f}_{il}$ of can be used to yield the acceleration demanded. At present $\underline{f}_{i0}, \bar{f}_{i0}$ and $\underline{f}_{il}, \bar{f}_{il}$ are selected by trials. Several illustrative example are used to show the pertinent features of the modified method.

Numerical Example

Considered the following system

$$\begin{aligned} k_{11}(x, t, \underline{G}_1(t, \underline{F}(t, \underline{u}_{1n-1}(t, \alpha))) &= t^2 (\underline{u}_{1n-1}(t, \alpha))^2 \\ k_{12}(x, t, \bar{G}_2(t, \bar{F}(t, \bar{u}_{2n-1}(t, \alpha))) &= (x-t)t(\bar{u}_{2n-1}(t, \alpha))^2 \\ k_{21}(x, t, \underline{G}_1(t, \underline{F}(t, \underline{u}_{1n-1}(t, \alpha))) &= x^2t(\underline{u}_{1n-1}(t, \alpha))^2 \\ k_{22}(x, t, \bar{G}_2(t, \bar{F}(t, \bar{u}_{2n-1}(t, \alpha))) &= t^5(\bar{u}_{2n-1}(t, \alpha))^2 \\ \underline{f}_1(x, \alpha) &= x\alpha - \left(\frac{x^9}{72} + 0.00625 \right) \alpha^2 - x(0.000217(2-\alpha)^2 - 0.00074\alpha - 0.000217) \\ &\quad + (2-\alpha)^2 \left(0.0000977 - \frac{x^4}{4} + 0.0156 \right) \\ \bar{f}_1(x, \alpha) &= x(2-\alpha) - \alpha^2(0.0156 + 0.000977 - \frac{x^{10}}{90}) - x(0.00049(2-\alpha)^2 + \alpha^2) \\ &\quad + (2-\alpha)^2 \left(0.000217 - \frac{x^5}{5} + 0.00625 \right) \\ \underline{f}_{00}(x, \alpha) &= x^2(2-\alpha) - 0.00625x\alpha^2 - (2-\alpha)^2 \left(0.000044 + \frac{x^6}{4} - 0.0156x^2 + \frac{x^{10}}{10} - 0.000977 \right) \end{aligned}$$

$$\begin{aligned} \bar{f}_2(x, \alpha) &= x^2 v - 0.0156 x^2 \alpha^2 - 0.000217(2-\alpha)^2 - \frac{x^7}{5}(2-\alpha)^2 + \\ &x(2-\alpha)^2 0.000625 - \frac{x^{11}}{11} \alpha^2 + 0.000044 \alpha^2 \end{aligned}$$

The exact solutions for our system are

$$\begin{aligned} \underline{u}_1(x, \alpha) &= x\alpha \quad \text{and} \quad \bar{u}_1(x, \alpha) = x(2-\alpha) \\ \underline{u}_2(x, \alpha) &= x^2(2-\alpha) \quad \text{and} \quad \bar{u}_2(x, \alpha) = x^2 \end{aligned}$$

i=2 and m=2

$$\begin{aligned} \underline{u}_{1n}(x, \alpha) &= \\ &\underline{f}_1(x, \alpha) + \\ &\int_a^d k_{11}(x, t, \underline{G}_1(t, \underline{F}(t, \underline{u}_{1n-1}(t, \alpha)))) dt + \\ &\int_d^e k_{12}(x, t, \bar{G}_2(t, \bar{F}(t, \bar{u}_{2n-1}(t, \alpha)))) dt + \int_c^e k_{21}(x, t, \underline{G}_1(t, \underline{F}(t, \bar{u}_{2n-1}(t, \alpha)))) dt + \\ &\int_e^x k_{22}(x, t, \bar{G}_2(t, \underline{F}(t, \underline{u}_{2n-1}(t, \alpha)))) dt \\ \bar{u}_{1n}(x, \alpha) &= \\ &\bar{f}_1(x, \alpha) + \int_a^d k_{11}(x, t, \bar{G}_1(t, \bar{F}(t, \bar{u}_{2n-1}(t, \alpha)))) dt + \\ &\int_d^e k_{12}(x, t, k(x, t, \underline{G}_2(t, \underline{F}(t, \underline{u}_{2n-1}(t, \alpha)))) dt + \\ &\int_c^e k_{21}(x, t, \bar{G}_1(t, \underline{F}(t, \underline{u}_{2n-1}(t, \alpha)))) dt + \\ &\int_e^x k_{22}(x, t, \underline{G}_2(t, \bar{F}(t, \bar{u}_{2n-1}(t, \alpha)))) dt \\ \underline{u}_{2n}(x, \alpha) &= \\ &\underline{f}_2(x, \alpha) + \\ &\int_a^d k_{11}(x, t, \underline{G}_1(t, \underline{F}(t, \underline{u}_{1n-1}(t, \alpha)))) dt + \\ &\int_d^e k_{12}(x, t, \bar{G}_2(t, \bar{F}(t, \bar{u}_{2n-1}(t, \alpha)))) dt + \int_c^e k_{21}(x, t, \underline{G}_1(t, \bar{F}(t, \bar{u}_{2n-1}(t, \alpha)))) dt + \\ &\int_e^x k_{22}(x, t, \underline{G}_2(t, \underline{F}(t, \underline{u}_{2n-1}(t, \alpha)))) dt \end{aligned}$$

$$\begin{aligned} \bar{u}_{2n}(x, \alpha) &= \\ &\bar{f}_2(x, \alpha) + \int_a^d k_{11}(x, t, \bar{G}_1(t, \underline{F}(t, \underline{u}_{1n-1}(t, \alpha)))) dt + \\ &\int_d^e k_{12}(x, t, \bar{G}_2(t, \underline{F}(t, \underline{u}_{1n-1}(t, \alpha)))) dt + \\ &\int_c^x k_{21}(x, t, \bar{G}_1(t, \bar{F}(t, \bar{u}_{2n-1}(t, \alpha)))) dt + \\ &\int_e^x k_{22}(x, t, \underline{F}(t, \bar{u}_{2n-1}(t, \alpha))) dt \\ n &= 0, 1, \dots \end{aligned}$$

Now we applied modified decompositions method to solve our system (Tables 1-4)

$$\begin{aligned} \underline{f}_1(x, \alpha) &= \underline{f}_{10}(x, \alpha) + \underline{f}_{11}(x, \alpha) \\ \bar{f}_1(x, \alpha) &= \bar{f}_{10}(x, \alpha) + \bar{f}_{11}(x, \alpha) \\ f_2(x, \alpha) &= \underline{f}_{20}(x, \alpha) + \underline{f}_{21}(x, \alpha) \\ \bar{f}_2(x, \alpha) &= \bar{f}_{20}(x, \alpha) + \bar{f}_{21}(x, \alpha) \\ \underline{f}_{10}(x, \alpha) &= xa \\ \underline{f}_{11}(x, \alpha) &= -\left(\frac{x^9}{72} + 0.00625\right)\alpha^2 - \\ &x\left(0.000217(2-\alpha)^2 - 0.00074\alpha - 0.000217\right) + \\ &(2-\alpha)^2\left(0.0000977 - \frac{x^4}{4} + 0.0156\right) \\ \bar{f}_{10}(x, \alpha) &= x(2-\alpha) \\ \bar{f}_{11}(x, \alpha) &= -\alpha^2(0.0156 + 0.000977 - \\ &\frac{x^{10}}{90} - x\left(0.00049(2-\alpha)^2 + \alpha^2\right) + (2-\alpha)^2\left(0.000217 - \frac{x^5}{5} + 0.00625\right)) \\ \underline{f}_{20}(x, \alpha) &= x^2(2-\alpha) \\ \underline{f}_{21}(x, \alpha) &= -0.00625xa^2 - (2-\alpha)^2\left(0.000044 + \frac{x^6}{4} - 0.0156x^2 + \frac{x^{10}}{10} - 0.000977\right) \\ \bar{f}_{20}(x, \alpha) &= x^2\alpha \end{aligned}$$

X	\bar{u}_{11}						MDM						Absolute error					
	0.1	0.3	0.5	0.7	0.9	1.0	0.1	0.3	0.5	0.7	0.9	1.0	0.0	0.0	0.0	0.0	0.0	0.0
0	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
0.2	0.02	0.06	0.10	0.14	0.18	0.20	0.02	0.06	0.10	0.14	0.18	0.20	0.000	0.000	0.000	0.000	0.000	0.000
0.4	0.04	0.12	0.20	0.28	0.36	0.40	0.04	0.12	0.20	0.28	0.36	0.40	0.000	0.000	0.000	0.000	0.000	0.000
0.6	0.06	0.18	0.30	0.42	0.54	0.60	0.06	0.18	0.30	0.42	0.54	0.60	0.000	0.000	0.000	0.000	0.000	0.000
0.8	0.08	0.24	0.40	0.56	0.72	0.80	0.08	0.24	0.40	0.56	0.72	0.80	0.000	0.000	0.000	0.000	0.000	0.000
1.0	0.01	0.30	0.50	0.70	0.90	0.10	0.01	0.30	0.50	0.70	0.90	0.10	0.000	0.000	0.000	0.000	0.000	0.000

Table 1: Compared between the exact solution and MDM for \bar{u}_{11} .

X	\bar{u}_{11}						MDM						Absolute error					
	0.1	0.3	0.5	0.7	0.9	1.0	0.1	0.3	0.5	0.7	0.9	1.0	0.1	0.3	0.	0.7	0.9	1.0
0	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.000	0.000	0.000	0.000	0.000	0.000
0.2	0.38	0.34	0.30	0.26	0.22	0.20	0.38	0.34	0.30	0.26	0.22	0.20	0.000	0.000	0.000	0.000	0.000	0.000
0.4	0.76	0.68	0.60	0.52	0.44	0.40	0.76	0.68	0.60	0.52	0.44	0.40	0.000	0.000	0.000	0.000	0.000	0.000
0.6	1.14	1.02	0.90	0.78	0.66	0.60	1.14	1.02	0.90	0.78	0.66	0.60	0.000	0.000	0.000	0.000	0.000	0.000
0.8	1.52	1.36	1.20	1.04	0.88	0.80	1.52	1.36	1.20	1.04	0.88	0.80	0.000	0.000	0.000	0.000	0.000	0.000
1.0	1.90	1.70	1.50	1.30	1.11	1.00	1.90	1.70	1.50	1.30	1.11	1.00	0.000	0.000	0.000	0.000	0.000	0.000

Table 2: Compared between the exact solution and MDM for \bar{u}_{11} .

X	\underline{u}_{11}						MDM						Absolute error						
	α	0.1	0.3	0.5	0.7	0.9	1.0	0.1	0.3	0.5	0.7	0.9	1.0	0.1	0.3	0.	0.7	0.9	1.0
0	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0000	000	000	000	000	000	000
0.2	0.38	0.34	0.30	0.26	0.22	0.20	0.38	0.34	0.30	0.26	0.22	0.20	0000	000	000	000	000	000	000
0.4	0.76	0.68	0.60	0.52	0.44	0.40	0.76	0.68	0.60	0.52	0.44	0.40	0000	000	000	000	000	000	000
0.6	1.14	1.02	0.90	0.78	0.66	0.60	1.14	1.02	0.90	0.78	0.66	0.60	0000	000	000	000	000	000	000
0.8	1.52	1.36	1.20	1.04	0.88	0.80	1.52	1.36	1.20	1.04	0.88	0.80	0000	000	000	000	000	000	000
1.0	1.90	1.70	1.50	1.30	1.11	1.00	1.90	1.70	1.50	1.30	1.11	1.00	0000	000	000	000	000	000	000

Table 3: Compared between the exact solution and MDM for \underline{u}_{12} .

X	\underline{u}_{12}						MDM						Absolute error						
	α	0.1	0.3	0.5	0.7	0.9	1.0	0.1	0.3	0.5	0.7	0.9	1.0	0.1	0.3	0.	0.7	0.9	1.0
0	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0000	000	000	000	000	000	000
0.2	.076	.068	.06	.052	.044	.04	.076	.068	.06	.052	.044	.04	0000	000	000	000	000	000	000
0.4	.304	.272	.24	.208	.176	.16	.304	.272	.24	.208	.176	.16	0000	000	000	000	000	000	000
0.6	.684	.612	.54	.612	.396	.36	.684	.612	.54	.612	.396	.36	0000	000	000	000	000	000	000
0.8	1.22	1.088	.96	.832	.704	.64	1.22	1.088	.96	.832	.704	.64	0000	000	000	000	000	000	000
1.0	1.9	1.7	1.5	1.3	1.1	1.0	1.9	1.7	1.5	1.3	1.1	1.0	0000	000	000	000	000	000	000

Table 4: Compared between the exact solution and MDM for \underline{u}_{22} .

$$\bar{f}_{21}(x, \alpha) = -0.0156x^2\alpha^2 - 0.000217(2-\alpha)^2 - \frac{x^5}{5}(2-\alpha)^2 + x(2-\alpha)^2 0.000625 - \frac{x^{11}}{11}\alpha^2 + 0.000044\alpha^2$$

$$\underline{u}_{10}(x, \alpha) = \bar{f}_{10}(x, \alpha) = x\alpha$$

$$\overline{u}_{10}(x, \alpha) = \bar{f}_{10}(x, \alpha) = x(2-\alpha)$$

$$\underline{u}_{20}(x, \alpha) = \bar{f}_{20}(x, \alpha) = x^2(2-\alpha)$$

$$\overline{u}_{20}(x, \alpha) = \bar{f}_{20}(x, \alpha) = x^2\alpha$$

$$\underline{u}_{11}(x, \alpha) = \bar{f}_{11}(x, \alpha) + \int_a^d t^2 (\underline{u}_{10}(t, \alpha))^2 dt + \int_d^c (x-t)t(\overline{u}_{20}(t, \alpha))^2 dt + \int_c^x x^2 t (\overline{u}_{10}(t, \alpha))^2 dt + \int_t^x (\underline{u}_{20}(t, \alpha))^2 dt = 0$$

$$\overline{u}_{11}(x, \alpha) =$$

$$\bar{f}_{11}(x, \alpha) + \int_a^d t^2 (\overline{u}_{10}(t, \alpha))^2 dt + \int_d^c (x-t)t(\underline{u}_{20}(t, \alpha))^2 dt +$$

$$\int_c^x x^2 t (\underline{u}_{10}(t, \alpha))^2 dt + \int_t^x (\overline{u}_{20}(t, \alpha))^2 dt = 0$$

$$\underline{u}_{21}(x, \alpha) =$$

$$\bar{f}_{21}(x, \alpha) + \int_a^d t^2 ((\underline{u}_{1n-1}(t, \alpha)))^2 dt + \int_d^c (x-t)t((\overline{u}_{20}(t, \alpha)))^2 dt +$$

$$\int_c^x x^2 t ((\overline{u}_{10}(t, \alpha)))^2 dt + \int_t^x (\underline{u}_{20}(t, \alpha))^2 dt = 0$$

$$\overline{u}_{21}(x, \alpha) =$$

$$\bar{f}_{21}(x, \alpha) + \int_a^d t^2 ((\overline{u}_{10}(t, \alpha)))^2 dt +$$

$$\int_d^c (x-t)t((\underline{u}_{20}(t, \alpha)))^2 dt + \int_c^x x^2 t ((\underline{u}_{10}(t, \alpha)))^2 dt + \int_t^x (\overline{u}_{20}(t, \alpha))^2 dt = 0$$

Where

$$a=0, d=0.25, c=0.45, e=0.75.$$

Conclusion

This paper we are using technique for modified decomposition

method to solve system of fuzzy nonlinear integral equation, the method above is implemented in a straight forward manner and proved by using only two iteration to get the exact solution, this technique is so fast and easy to get the converge for solve any equation and system for any value of α . The modified admian method there is one important note the exact solution must be a part of the nonhomogeneous function or series of nonhomogeneous.

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