Moufang loops and generalized Lie-Cartan theorem¹

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Abstract

Generalized Lie-Cartan theorem for linear birepresentations of an analytic Moufang loop is considered. The commutation relations of the generators of the birepresentation are found. In particular, the Lie algebra of the multiplication group of the birepresentation is explicitly given.

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Dedicated to Maks A. Akivis on the occasion of his 85th birthday and 65 years of scientific activity

1 Introduction

Continuous symmetries generated by the Lie transformation groups are widely exploited in modern mathematics and physics. Nevertheless, it may happen that the group theoretical methods are too rigid and one has to extend these beyond the Lie groups and algebras. From this point of view it is interesting to extend the group theoretical symmetry methods by using the Moufang loops and Mal'tsev algebras. The latter are known as minimal non-associative generalizations of the group and Lie algebra concepts, respectively.

In this paper, the generalized Lie-Cartan theorem for linear birepresentations of an analytic Moufang loop is considered. The commutation relations of the generators of the birepresentation were found. In particular, the Lie algebra of the multiplication group of the birepresentation is explicitly given.

Based on this theorem, various applications are possible. In particular, it was recently shown [6] how the Moufang-Noether current algebras may be constructed so that the corresponding Noether charge algebra turns out to be a birepresentation of the tangent Mal'tsev algebra of an analytic Moufang loop.

2 Moufang loops

A Moufang loop [2, 1, 3] is a quasigroup G with the unit element $e \in G$ and the Moufang identity

$$(ag)(ha) = a(gh)a, \qquad a, g, h \in G$$

Here the multiplication is denoted by juxtaposition. In general, the multiplication need not be associative: $gh \cdot a \neq g \cdot ha$ for some triple of elements $a, g, h \in G$. The inverse element g^{-1} of g is defined by

 $gg^{-1} = g^{-1}g = e$

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3 Analytic Moufang loops and Mal'tsev algebras

Following the concept of the Lie group, the notion of an analytic Moufang loop can be easily formulated.

A Moufang loop G is said [4] to be *analytic* if G is also a real analytic manifold and main operations - multiplication and inversion map $g \mapsto g^{-1}$ - are analytic mappings.

Let the local coordinates of g from the vicinity of $e \in G$ be denoted by g^i $(i = 1, ..., r \doteq \dim G)$. The tangent space of G at $e \in G$ is denoted by $T_e(G)$.

As in the case of the Lie groups, the structure constants c_{jk}^i of an analytic Moufang loop are defined by

$$c_{jk}^{i} \doteq \frac{\partial^{2}(ghg^{-1}h^{-1})^{i}}{\partial g^{j}\partial h^{k}}\Big|_{g=h=e} = -c_{kj}^{i}, \qquad i, j, k = 1, \dots, r$$

For any $x, y \in T_e(G)$, their (tangent) product $[x, y] \in T_e(G)$ is defined in component form by

$$[x,y]^{i} \doteq c^{i}_{jk}x^{j}y^{k} = -[y,x]^{i}, \qquad i = 1, \dots, r$$

The tangent space $T_e(G)$ being equipped with such an anti-commutative multiplication is called the *tangent algebra* of the analytic Moufang loop G. We shall use the notation $\Gamma \doteq \{T_e(G), [\cdot, \cdot]\}$ for the tangent algebra of G.

The tangent algebra of G need not be a Lie algebra. There may exist a triple $x, y, z \in T_e(G)$ that does not satisfy the Jacobi identity:

$$J(x, y, z) \doteq [x, [y, z]] + [y, [z, x]] + [z, [x, y]] \neq 0$$

Instead, for all $x, y, z \in T_e(G)$ one has a more general Mal'tsev identity [4]

$$[J(x, y, z), x] = J(x, y, [x, z])$$

Anti-commutative algebras with this identity are called the Mal'tsev algebras.

4 Birepresentation of a Moufang loop

Consider a pair (S,T) of the maps $g \mapsto S_g$, $g \mapsto T_g$ of a Moufang loop G into GL_n . The pair (S,T) is called [5] a (linear) *birepresentation* of G (in GL_n) if the following conditions hold true:

• $S_e = T_e = \mathrm{id},$

•
$$T_g S_g S_h = S_{gh} T_g,$$

• $S_g T_g T_h = T_{hg} S_g$.

The birepresentation (S, T) is called *associative*, if the following simultaneous relations are satisfied:

$$S_g S_h = S_{gh}, \quad T_g T_h = T_{hg}, \quad S_g T_h = T_h S_g, \qquad \forall g, h \in G$$

In general, birepresentations need not be associative even for groups.

5 Generators and structure functions

The generators of a birepresentation (S, T) are defined as follows:

$$S_j \doteq \frac{\partial S_g}{\partial g^j} \bigg|_{g=e}, \qquad T_j \doteq \frac{\partial T_g}{\partial g^j} \bigg|_{g=e}, \qquad j = 1, \dots, r$$

The *auxiliary functions* of G are defined as

$$v_j^n(g) \doteq \frac{\partial (gh)^n}{\partial h^j}\Big|_{h=e}, \qquad n, j = 1, \dots, r$$

The structure functions $c_{ik}^n(g)$ of G are defined by the generalized Maurer-Cartan equations

$$v_j^n(g)\frac{\partial v_k^i(g)}{\partial g^n} - v_k^n(g)\frac{\partial v_j^i(g)}{\partial g^n} \doteq c_{jk}^n(g)v_n^i(g)$$

One can check the initial conditions

$$c_{jk}^n(e) = c_{jk}^n$$

The algebra with structure functions $c_{jk}^n(g)$ may be called the *derivative* of the tangent algebra Γ of G. It follows from the Belousov theory [1] of *derivative quasigroups and loops* that the derivative of the tangent Mal'tsev algebra of G is a Mal'tsev algebra as well. In a sense, the derivative Mal'tsev algebra is a deformation of Γ with the deformation parameter $g \in G$.

6 Generalized Lie equations (GLE)

Define the *derivative generators* of (S, T) as follows:

$$S_j(g) \doteq T_g S_j T_g^{-1}, \quad T_j(g) \doteq S_g^{-1} T_j S_g$$

By direct calculations, one can check that

$$S_j(g) + T_j(g) = S_j + T_j$$

In what follows, the *commutator* of linear operators A, B is denoted as $[A, B] \doteq AB - BA$.

Theorem 1 (generalized Lie equations). Let (S,T) be a differentiable birepresentation of an analytic Moufang loop G. Then the birepresentation matrices S_g, T_g $(g \in G)$ satisfy the system of simultaneous differential equations

$$v_{j}^{n}(g)\frac{\partial S_{g}}{\partial g^{n}} = S_{g} \underbrace{T_{g}S_{j}T_{g}^{-1}}_{associator} = S_{g}S_{j}(g)$$
$$= S_{g}S_{j} + \underbrace{[S_{g}, T_{j}]}_{associator}$$
$$v_{j}^{n}(g)\frac{\partial T_{g}}{\partial g^{n}} = \underbrace{T_{g}^{-1}T_{j}S_{g}}_{g}T_{g} = T_{j}(g)T_{g}$$
$$= T_{j}T_{g} + \underbrace{[S_{j}, T_{g}]}_{associator}.$$

Proof. Differentiate the defining relations of a birepresentation (S,T) with respect to g and take g = e.

7 Generalized Lie-Cartan theorem

Theorem 2 (generalized Lie-Cartan theorem). The integrability conditions of GLE read as commutation relations

$$[S_j(g), S_k(g)] = c_{jk}^n(g)S_n(g) - 2[S_j(g), T_k(g)]$$

$$[T_j(g), T_k(g)] = -c_{jk}^n(g)T_n(g) - 2[T_j(g), S_k(g)]$$

Proof. Differentiate the GLE and use

$$\frac{\partial^2 S_g}{\partial g^j \partial g^k} = \frac{\partial^2 S_g}{\partial g^k \partial g^j}, \qquad \frac{\partial^2 T_g}{\partial g^j \partial g^k} = \frac{\partial^2 T_g}{\partial g^k \partial g^j} \qquad \Box$$

Corollary 3. If (S,T) is an associative birepresentation of a Lie group G, then one gets the well known Lie algebra commutation relations (Lie-Cartan theorem)

$$[S_j, S_k] - c_{jk}^n S_n = [T_j, T_k] + c_{jk}^n T_n = [S_j, T_k] = 0$$

8 Yamagutian and Yamaguti brackets

Let $g \in G$ and $x, y \in T_e(G)$. Denote

$$S_x(g) \doteq x^j S_j(g), \qquad T_x(g) \doteq x^j T_j(g), \qquad [x, y]_g^i \doteq c_{jk}^i(g) x^j y^k, \quad i = 1, \dots, r$$

Define the Yamagutian Y_g by

$$3Y_g(x;y) \doteq [S_x(g), S_y(g)] + [S_x(g), T_y(g)] + [T_x(g), T_y(g)]$$

By direct calulations one can check that the Yamagutian obeys the constraints

$$\begin{split} Y_g(x;y) + Y_g(y;x) &= 0\\ Y_g([x,y]_g;z) + Y_g([y,z]_g;x) + Y_g([z,x]_g;y) &= 0 \end{split}$$

The Yamaguti brackets $[\cdot, \cdot, \cdot]_g$ are defined [8, 9] in $T_e(G)$ by

$$\begin{split} [x, y, z]_g &\doteq [x, [y, z]_g]_g - [y, [x, z]_g]_g + [[x, y]_g, z]_g \\ &= J_g(x, y, z) + 2[[x, y]_g, z]_g \end{split}$$

9 Closure of integrability conditions

It turns out that the commutation relations for derivative generators of the birepresentation (S, T) can be presented in a closed Lie algebra form.

The integrability conditions of GLE can be written as follows:

$$[S_x(g), S_y(g)] = 2Y_g(x; y) + \frac{1}{3}S_{[x,y]_g}(g) + \frac{2}{3}T_{[x,y]_g}(g)$$
(1)

$$[S_x(g), T_y(g)] = -Y_g(x; y) + \frac{1}{3}S_{[x,y]_g}(g) - \frac{1}{3}T_{[x,y]_g}(g)$$
(2)

$$[T_x(g), T_y(g)] = 2Y_g(x; y) - \frac{2}{3}S_{[x,y]_g}(g) - \frac{1}{3}T_{[x,y]_g}(g)$$
(3)

One can prove the *reductivity conditions* [5]

$$6[Y_g(x;y), S_z(g)] = S_{[x,y,z]_g}(g)$$
(4)

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$$6[Y_g(x;y), T_z(g)] = T_{[x,y,z]_g}(g)$$
(5)

By using the above reductivity conditions it can be shown by direct calculations that the Yamagutian obeys the Lie algebra

$$6[Y_g(x;y), Y_g(z;w)] = Y_g([x,y,z]_g;w) + Y_g(z;[x,y,w]_g)$$
(6)

Dimension of the Lie algebra (1) - (6) does not exceed 2r + r(r-1)/2. The Jacobi identities are guaranteed by the defining identities of the *Lie* [7] and *general Lie triple systems* [8, 9] associated with the derivative Mal'tsev algebra of $T_e(G)$ of G.

The commutation relations of form (1) - (6) are well known from the theory of *alternative* algebras [10]. By taking g = e, the commutation relations (1) - (6) give the Lie algebra of the *multiplication group of the birepresentation* (S,T) of G. For field theoretical applications see [6].

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