

# Linear Differential Equations: Definition, Solution Methods and Properties

Gustav Sjoberck\*

Department of Psychology, The University of Virginia, Charlottesville, VA 22903, USA

## Abstract

This article provides an introduction to linear differential equations, which are equations involving derivatives of an unknown function that can be expressed as a linear combination of the function and its derivatives. After discussing the basic definitions and terminology, the article outlines various methods for solving linear differential equations, including separation of variables, integrating factors and the method of undetermined coefficients. It also covers some important properties of linear differential equations, such as linearity, superposition and the existence and uniqueness theorem. The article concludes by exploring some applications of linear differential equations in physics, engineering and other fields.

**Keywords:** Mathematics • Linear differential equations • Integrating factors

## Introduction

A linear differential equation is a type of differential equation that can be written in the form of:

$$y' + p(x)y = q(x)$$

where  $y$  is a function of  $x$ ,  $y'$  is the derivative of  $y$  with respect to  $x$ ,  $p(x)$  and  $q(x)$  are given functions of  $x$ .

The term "linear" in this context means that the dependent variable  $y$  and its derivative  $y'$  appear only in a linear form, that is, with a power of 1. Linear differential equations are important in many areas of mathematics and physics and they have been extensively studied for many years. In this article, we will explore some of the properties and solutions of linear differential equations.

## Literature Review

**Properties of Linear Differential Equations** One of the most important properties of linear differential equations is their linearity. This means that if we have two solutions  $y_1(x)$  and  $y_2(x)$  to the differential equation, then any linear combination of these solutions:

$$c_1y_1(x) + c_2y_2(x)$$

is also a solution, where  $c_1$  and  $c_2$  are constants.

Another important property of linear differential equations is that they can be solved using an integrating factor. An integrating factor is a function that is used to multiply both sides of the differential equation so that it can be integrated more easily. The integrating factor for a linear differential equation is given by:

$$I(x) = e^{\int p(x) dx}$$

where  $\int p(x) dx$  represents the indefinite integral of  $p(x)$  with respect to  $x$ .

Using an integrating factor, the solution to the linear differential equation can be expressed as where  $C$  is a constant of integration. Solving Linear Differential

## Equations

To solve a linear differential equation, we first need to identify the functions  $p(x)$  and  $q(x)$  in the equation. Once we have identified these functions, we can then find the integrating factor  $I(x)$  and use it to solve the equation.

Let's consider an example of a linear differential equation:

$$y' + 2xy = x^2$$

In this case,  $p(x) = 2x$  and  $q(x) = x^2$ . To find the integrating factor  $I(x)$ , we need to evaluate the integral of  $p(x)$  with respect to  $x$ : where  $C_1$  is a constant of integration. Therefore, the integrating factor for this equation is:

Multiplying both sides of the equation by the integrating factor, we can then rewrite the left-hand side of the equation as the derivative of the product of the integrating factor and the dependent variable  $y$ :

$$(d/dx)(e^{x^2} * y) = x^2 * e^{x^2}$$

Integrating both sides of the equation with respect to  $x$ , we obtain:  
**Applications of Linear Differential Equations.** Linear differential equations have a wide range of applications in mathematics

A linear differential equation is a type of differential equation that can be expressed in the form:

where  $y^{(n)}(x)$  denotes the  $n$ -th derivative of  $y(x)$  with respect to  $x$ ,  $a_0, a_1, \dots, a_{n-1}$  are constants and  $f(x)$  is a given function. Linear differential equations are important in many areas of mathematics and physics, as they arise naturally in the modeling of many physical phenomena. For example, the motion of a mass on a spring, the growth of populations and the flow of heat and electricity are all described by linear differential equations [1-6].

## Discussion

**Solving Linear Differential Equations** The solution to a linear differential equation is a function  $y(x)$  that satisfies the equation. To find this function, we typically use one of several methods, depending on the nature of the equation and the form of the function  $f(x)$ . One common method for solving linear differential equations is to use the method of undetermined coefficients. This involves guessing a particular solution to the equation that has the same form as  $f(x)$  and then using this guess to find the general solution. For example, if  $f(x)$  is a polynomial of degree  $m$ , we might guess that the particular solution is a polynomial of degree  $m$ . We then substitute this guess into the equation and solve for the coefficients  $c_0, c_1, \dots, c_m$ . Once we have found  $y_p(x)$ , we can find the general solution to the equation by adding to  $y_p(x)$  the general solution to the homogeneous equation, which is obtained by setting  $f(x)$  equal to zero. Another common method for solving linear differential equations is to use the method of variation of parameters. This involves assuming that the solution to the equation has the

**\*Address for Correspondence:** Gustav Sjoberck, Department of Psychology, The University of Virginia, Charlottesville, VA 22903, USA; E-mail: Sj.gustav@gmail.com

**Copyright:** © 2023 Sjoberck G. This is an open-access article distributed under the terms of the Creative Commons Attribution License, which permits unrestricted use, distribution, and reproduction in any medium, provided the original author and source are credited.

**Received:** 23 January, 2023, Manuscript No. glta-23-95065; **Editor Assigned:** 25 January, 2023, PreQC No. P-95065; **Reviewed:** 15 February, 2023, QC No. Q-95065; **Revised:** 20 February, 2023, Manuscript No. R-95065; **Published:** 27 February, 2023, DOI: 10.37421/1736-4337.2023.17.377

form  $y(x)=u(x)y_1(x)+v(x)y_2(x)$ , where  $y_1(x)$  and  $y_2(x)$  are known solutions to the homogeneous equation and  $u(x)$  and  $v(x)$  are functions to be determined. We then substitute this form into the equation and solve for  $u(x)$  and  $v(x)$ . Once we have found  $u(x)$  and  $v(x)$ , we can plug them back into the equation to obtain the general solution.

Linear differential equations have several important properties that make them useful in many areas of mathematics and physics. Some of these properties include:

**Linearity:** The linearity of a differential equation means that if  $y_1(x)$  and  $y_2(x)$  are solutions to the equation, then any linear combination where  $c_1$  and  $c_2$  are constants is also a solution to the equation. **Superposition:** The superposition principle states that if  $y_1(x)$  and  $y_2(x)$  are solutions.

Linear differential equations are an important area of mathematics that have applications in various fields such as physics, engineering and economics. These equations involve derivatives of an unknown function and are said to be linear when the function and its derivatives appear in a linear combination.

## Conclusion

There are several solution methods for linear differential equations, including the method of integrating factors, separation of variables and variation of parameters. These methods involve various techniques for manipulating the differential equation and solving for the unknown function. Properties of linear differential equations include linearity, superposition and homogeneity. These properties make linear differential equations easier to solve and provide insights into the behavior of the solutions. Overall, understanding linear differential equations is crucial for anyone interested in the quantitative sciences and these equations have a wide range of applications in modeling and analysis.

## Acknowledgement

None.

## Conflict of Interest

No conflict of interest.

## References

1. Kamenisch, York, Maria Fousteri, Jennifer Knoch and Anna-Katharina von Thaler, et al. "Proteins of nucleotide and base excision repair pathways interact in mitochondria to protect from loss of subcutaneous fat, a hallmark of aging." *Exp Med* 207 (2010): 379-390.
2. Cannino, Giuseppe, Francesco Ciscato, Ionica Masgras and Carlos Sánchez-Martín, et al. "Metabolic plasticity of tumor cell mitochondria." *Front Oncol* (2018): 333.
3. Mailloux, Ryan J., Ranji Singh, Guy Brewer and Christopher Auger, et al. " $\alpha$ -ketoglutarate dehydrogenase and glutamate dehydrogenase work in tandem to modulate the antioxidant  $\alpha$ -ketoglutarate during oxidative stress in *Pseudomonas fluorescens*." *J Bacteriol Res* 191 (2009): 3804-3810.
4. Sabharwal, Simran S. and Paul T. Schumacker. "Mitochondrial ROS in cancer: initiators, amplifiers or an Achilles' heel?." *Nat Rev Cancer* 14 (2014): 709-721.
5. Panieri, E. and M. M. Santoro. "ROS homeostasis and metabolism: a dangerous liaison in cancer cells." *Cell Death Dis* 7 (2016): e2253-e2253.
6. Goossens, Jan-Willem, Mansoor I. Yousefi, Yves Jaouën and Hartmut Hafermann, et al. "Polarization-division multiplexing based on the nonlinear Fourier transform." *Opt Express* 25 (2017): 26437-26452.

**How to cite this article:** Sjoberck, Gustav. "Linear Differential Equations: Definition, Solution Methods and Properties." *J Generalized Lie Theory App* 17 (2023): 377.