

Research Article

Dynamical Yang-Baxter Maps Associated with Homogeneous Pre-Systems*

Noriaki Kamiya¹ and Youichi Shibukawa²

Dedicated to Professor Susumu Okubo on the occasion of his eightieth birthday

¹Center for Mathematical Sciences, University of Aizu, Aizuwakamatsu, Fukushima 965-8580, Japan

²Department of Mathematics, Faculty of Science, Hokkaido University, Sapporo, Hokkaido 060-0810, Japan
Address correspondence to Youichi Shibukawa, shibu@math.sci.hokudai.ac.jp

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Abstract We construct dynamical Yang-Baxter maps, which are set-theoretical solutions to a version of the quantum dynamical Yang-Baxter equation, by means of homogeneous pre-systems, that is, ternary systems encoded in the reductive homogeneous space satisfying suitable conditions. Moreover, a characterization of these dynamical Yang-Baxter maps is presented.

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1 Introduction

The quantum dynamical Yang-Baxter equation (QDYBE for short) [9, 10], a generalization of the quantum Yang-Baxter equation (QYBE for short) [2, 3, 40, 41], has been studied extensively in recent years (see [7] and the references therein). Dynamical Yang-Baxter maps [31, 32, 34] are set-theoretical solutions to a version of the QDYBE.

Let H and X be nonempty sets with a map $(\cdot) : H \times X \ni (\lambda, x) \mapsto \lambda \cdot x \in H$. A map $R(\lambda) : X \times X \rightarrow X \times X$ ($\lambda \in H$) is a dynamical Yang-Baxter map associated with H , X and (\cdot) , if and only if, for every $\lambda \in H$, $R(\lambda)$ satisfies the following equation on $X \times X \times X$:

$$R_{23}(\lambda)R_{13}(\lambda \cdot X^{(2)})R_{12}(\lambda) = R_{12}(\lambda \cdot X^{(3)})R_{13}(\lambda)R_{23}(\lambda \cdot X^{(1)}). \quad (1.1)$$

Here $R_{12}(\lambda)$, $R_{12}(\lambda \cdot X^{(3)})$, $R_{23}(\lambda \cdot X^{(1)})$, and others are the maps from $X \times X \times X$ to itself defined as follows: for $u, v, w \in X$,

$$\begin{aligned} R_{12}(\lambda)(u, v, w) &= (R(\lambda)(u, v), w), \\ R_{12}(\lambda \cdot X^{(3)})(u, v, w) &= R_{12}(\lambda \cdot w)(u, v, w), \\ R_{23}(\lambda \cdot X^{(1)})(u, v, w) &= (u, R(\lambda \cdot u)(v, w)). \end{aligned}$$

Set-theoretical solutions to the QYBE [6], also known as Yang-Baxter maps [39], are dynamical Yang-Baxter maps constant for the parameter λ of any set H ; indeed, the dynamical Yang-Baxter map is a generalization of the set-theoretical solution to the QYBE.

This dynamical Yang-Baxter map yields a bialgebroid [4]. Every dynamical Yang-Baxter map with some conditions gives birth to an (H, X) -bialgebroid [35], a generalization of the quantum group [5, 11], through the Faddeev-Reshetikhin-Takhtajan construction [8].

It is worth pointing out that a ternary system (Definition 1(3)) can produce the dynamical Yang-Baxter map [32]. Each triple (L, M, π) consisting of a left quasigroup $L = (L, \cdot)$ (Definition 1(1)), a ternary system M satisfying (2.2) and (2.3), and a (set-theoretic) bijection $\pi : L \rightarrow M$ gives a dynamical Yang-Baxter map $R(\lambda)$ associated with L , L and (\cdot) (see Section 2 for more details).

Homogeneous systems [18, 19, 20, 21, 22, 23] are algebraic features of the reductive homogeneous space [24, 28] satisfying suitable conditions. Let A be a group with its subgroup K . We assume that a subset G of the group A satisfies the following:

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- (1) the group A is uniquely factorized as $A = GK$,
- (2) $G^{-1} = G$,
- (3) $kGk^{-1} = G$, for all $k \in K$.

Let $p : A \rightarrow G$ denote the canonical projection with respect to the factorization $A = GK$, and (\cdot) the binary operation on G defined by $x \cdot y = p(xy)$ ($x, y \in G$). Because the map $L_x : G \ni y \mapsto x \cdot y \in G$ is bijective, we define the ternary operation η on G by

$$\eta(x, y, z) = L_x\left(\left(L_x\right)^{-1}(y) \cdot \left(L_x\right)^{-1}(z)\right), \quad x, y, z \in G.$$

This ternary system $G = (G, \eta)$ is a homogeneous system [23, Proposition 1] (see also Definition 7), and every homogeneous system is constructed in such a way.

If G is a connected and second countable C^∞ -manifold with a C^∞ -map $\eta : G \times G \times G \rightarrow G$, then the homogeneous system $G = (G, \eta)$ is isomorphic to a reductive homogeneous space A/K for a connected Lie group A with its closed subgroup K [19, Theorem 1]. The homogeneous system is a ternary system, an algebraic structure, encoded in the reductive homogeneous space (for ternary systems in differential geometry and mathematical physics, see [13, 14, 15, 29]).

It is natural to relate this homogeneous system to the dynamical Yang-Baxter map through the ternary system.

The aim of this paper is to produce the dynamical Yang-Baxter maps by means of homogeneous pre-systems, which generalize the homogeneous system. Furthermore, we characterize such dynamical Yang-Baxter maps.

The organization of this paper is as follows.

Section 2 contains a brief summary of the dynamical Yang-Baxter map. We focus on its construction by means of the ternary system. This construction yields a category \mathcal{A} concerning the ternary systems, which is equivalent to a category \mathcal{D} consisting of the dynamical Yang-Baxter maps.

Section 3 presents the notion of a homogeneous pre-system, together with examples.

In Section 4, our main results are stated and proved. Every homogeneous pre-system satisfying (4.1) can produce a dynamical Yang-Baxter map via the ternary system. More precisely, we construct a category \mathcal{H} , isomorphic to the category \mathcal{A} , by means of the homogeneous pre-systems with (4.1). Because the category \mathcal{A} is equivalent to the category \mathcal{D} , each object of \mathcal{H} gives a dynamical Yang-Baxter map; in particular, we demonstrate dynamical Yang-Baxter maps provided by a certain left quasigroup and the examples in Section 3.

The last section, Section 5, deals with a relation between the homogeneous pre-system satisfying (4.1) and the left quasigroup with (5.1), which is due to the work in [32, Section 6]. We introduce a category \mathcal{B} concerning the left quasigroups satisfying (5.1) and an essentially surjective functor $J : \mathcal{B} \rightarrow \mathcal{H}$ to construct the dynamical Yang-Baxter maps by means of quasigroups of reflection [17, 27].

Our viewpoint sheds some light on the relation between geometry and the dynamical Yang-Baxter map.

2 Dynamical Yang-Baxter maps

In this section, we briefly summarize without proofs the relevant material in [32] on the construction of the dynamical Yang-Baxter map.

- Definition 1.** (1) (L, \cdot) is a left quasigroup (resp. right quasigroup [38, Section I.4.3]), if and only if L is a nonempty set, together with a binary operation (\cdot) on L having the property that, for all $u, w \in L$, there uniquely exists $v \in L$ such that $u \cdot v = w$ (resp. $v \cdot u = w$). For the simplicity, one uses the notation uv instead of $u \cdot v$ ($u, v \in L$).
- (2) A quasigroup (Q, \cdot) is a left and right quasigroup (see [30, Definition I.1.1] and [38, Section I.2]).
- (3) A ternary system (M, μ) is a pair of a nonempty set M and a ternary operation $\mu : M \times M \times M \rightarrow M$.

By this definition, the left quasigroup $L = (L, \cdot)$ has another binary operation \backslash_L called a left division [38, Section I.2.2]. For $u, w \in L$, we denote by $u \backslash_L w$ the unique element $v \in L$ satisfying $uv = w$,

$$u \backslash_L w = v \iff uv = w. \quad (2.1)$$

The binary operation on the quasigroup is not always associative.

Example 2. We define the binary operation $(*)$ on the set $Q = \{1, 2, 3, 4, 5\}$ of five elements by Table 1. Here $1 * 2 = 3$. This $Q = (Q, *)$ is a quasigroup, because each element in Q appears once and only once in each row and in each column of Table 1 [30, Theorem I.1.3]. The binary operation $(*)$ is not associative, since $(1*2)*3 \neq 1*(2*3)$. This quasigroup Q is due to Nobusawa [27, Section 6, type 1]. However, the order of the binary operation $(*)$ in Table 1 is reversed.

*	1	2	3	4	5
1	1	3	5	2	4
2	5	2	4	1	3
3	4	1	3	5	2
4	3	5	2	4	1
5	2	4	1	3	5

Table 1: Binary operation (*) on Q.

Each ternary system $M = (M, \mu)$ satisfying

$$\mu(a, \mu(a, b, c), \mu(\mu(a, b, c), c, d)) = \mu(a, b, \mu(b, c, d)), \tag{2.2}$$

$$\mu(\mu(a, b, \mu(b, c, d)), \mu(b, c, d), d) = \mu(\mu(a, b, c), c, d), \tag{2.3}$$

for any $a, b, c, d \in M$, can provide a dynamical Yang-Baxter map [32, Theorem 3.2]. Let $L = (L, \cdot)$ be a left quasigroup isomorphic to M as sets, and $\pi : L \rightarrow M$ a (set-theoretic) bijection. For $\lambda, u \in L$, we define the maps $\xi_\lambda^{(L, M, \pi)}(u) : L \rightarrow L$ and $\eta_\lambda^{(L, M, \pi)}(u) : L \rightarrow L$ as follows: for $v \in L$,

$$\xi_\lambda^{(L, M, \pi)}(u)(v) = \lambda \setminus_L \pi^{-1}(\mu(\pi(\lambda), \pi(\lambda u), \pi((\lambda u)v))), \tag{2.4}$$

$$\eta_\lambda^{(L, M, \pi)}(u)(v) = (\lambda \xi_\lambda^{(L, M, \pi)}(v)(u)) \setminus_L ((\lambda v)u). \tag{2.5}$$

Let $R^{(L, M, \pi)}(\lambda)$ ($\lambda \in L$) denote the map from $L \times L$ to itself defined by

$$R^{(L, M, \pi)}(\lambda)(u, v) = (\eta_\lambda^{(L, M, \pi)}(v)(u), \xi_\lambda^{(L, M, \pi)}(u)(v)), \quad u, v \in L. \tag{2.6}$$

Theorem 3. *The map $R^{(L, M, \pi)}(\lambda)$ (2.6) is a dynamical Yang-Baxter map (1.1) associated with L, L and (\cdot) .*

We now introduce two categories \mathcal{A} and \mathcal{D} concerning a special class of the dynamical Yang-Baxter maps, which play a central role in this article.

The first task is to explain the category \mathcal{A} (cf. the category \mathcal{A}_2 in [32, Section 6]). We follow the notation of [16, Chapter XI]. Let $L = (L, \cdot)$ be a left quasigroup, $M = (M, \mu)$ a ternary system satisfying (2.2) and

$$\mu(a, b, b) = a, \quad \forall a, b \in M, \tag{2.7}$$

$$\mu(\mu(a, b, c), c, d) = \mu(a, b, d), \quad \forall a, b, c, d \in M, \tag{2.8}$$

and $\pi : L \rightarrow M$ a bijection. The object of \mathcal{A} is, by definition, a triple (L, M, π) .

The morphism $f : (L, (M, \mu), \pi) \rightarrow (L', (M', \mu'), \pi')$ of \mathcal{A} is a homomorphism $f : L \rightarrow L'$ of left quasigroups such that $h := \pi' \circ f \circ \pi^{-1} : M \rightarrow M'$ is a homomorphism of ternary systems; that is, the map $f : L \rightarrow L'$ satisfies

$$\begin{aligned} f(a \cdot_L b) &= f(a) \cdot_{L'} f(b), \quad \forall a, b \in L, \\ h(\mu(a, b, c)) &= \mu'(h(a), h(b), h(c)), \quad \forall a, b, c \in M. \end{aligned} \tag{2.9}$$

The identity id , the source $s(f)$ and the target $b(f)$ of a morphism $f : (L, M, \pi) \rightarrow (L', M', \pi')$, and the composition $g \circ f$ for morphisms $f : (L, M, \pi) \rightarrow (L', M', \pi')$ and $g : (L', M', \pi') \rightarrow (L'', M'', \pi'')$ are defined as follows: for an object $(L, M, \pi) \in \mathcal{A}$,

$$\begin{aligned} \text{id}_{(L, M, \pi)} &= \text{id}_L, \\ s(f : (L, M, \pi) \rightarrow (L', M', \pi')) &= (L, M, \pi), \\ b(f : (L, M, \pi) \rightarrow (L', M', \pi')) &= (L', M', \pi'), \end{aligned}$$

the composition $g \circ f$ is the usual one of the maps $f : L \rightarrow L'$ and $g : L' \rightarrow L''$.

Proposition 4. *\mathcal{A} is a category.*

The next task is to describe the category \mathcal{D} , which is exactly the category \mathcal{D}_2 in [32, Section 6]. The object of this category \mathcal{D} is a pair (L, R) of a left quasigroup $L = (L, \cdot)$ and a dynamical Yang-Baxter map $R(\lambda) : L \times L \rightarrow L \times L$ ($\lambda \in L$) satisfying

$$\begin{aligned}\xi_\lambda(u)((\lambda u) \setminus_L (\lambda u)) &= \lambda \setminus_L \lambda, \quad \forall \lambda, u \in L, \\ (\lambda \xi_\lambda(u)(v)) \eta_\lambda(v)(u) &= (\lambda u)v, \quad \forall \lambda, u, v \in L, \\ (\lambda \xi_\lambda(u)(v)) \xi_{\lambda \xi_\lambda(u)(v)}(\eta_\lambda(v)(u))(w) &= \lambda \xi_\lambda(u)((\lambda u) \setminus_L ((\lambda u)v)w), \quad \forall \lambda, u, v, w \in L.\end{aligned}$$

Here, $(\eta_\lambda(v)(u), \xi_\lambda(u)(v)) := R(\lambda)(u, v)$ ($\lambda, u, v \in L$).

The morphism $f : (L, R) \rightarrow (L', R')$ of \mathcal{D} is a homomorphism $f : L \rightarrow L'$ of left quasigroups satisfying

$$R'(f(\lambda)) \circ f \times f = f \times f \circ R(\lambda), \quad \forall \lambda \in L.$$

Proposition 5. \mathcal{D} is a category; the definitions of the identity, the source, the target and the composition are similar to those of the category \mathcal{A} .

We can construct functors $S : \mathcal{A} \rightarrow \mathcal{D}$ and $T : \mathcal{D} \rightarrow \mathcal{A}$, which establish an equivalence of the categories \mathcal{A} and \mathcal{D} (cf. [32, Proposition 6.15]): for $(L, M, \pi) \in \mathcal{A}$, set $S(L, M, \pi) = (L, R^{(L, M, \pi)})$. Here, $R^{(L, M, \pi)}(\lambda)$ is defined by (2.4), (2.5) and (2.6); for a morphism f of \mathcal{A} , write $S(f) = f$; for $(L, R) \in \mathcal{D}$, $T(L, R)$ denotes the triple $(L, (M, \mu), \text{id}_L)$, where $M = L$ as sets and $\mu(a, b, c) = a \xi_a(a \setminus_L b)(b \setminus_L c)$ ($a, b, c \in M (= L)$); for a morphism f of \mathcal{D} , set $T(f) = f$.

These functors S and T satisfy $ST = \text{id}_{\mathcal{D}}$, and $\theta(L, M, \pi) := \text{id}_L$ ($(L, M, \pi) \in \mathcal{A}$) gives a natural isomorphism $\theta : TS \rightarrow \text{id}_{\mathcal{A}}$. Thus, the following theorem holds.

Theorem 6. $S : \mathcal{A} \rightarrow \mathcal{D}$ is an equivalence of categories.

3 Homogeneous pre-systems

This section is devoted to introducing homogeneous pre-systems.

Definition 7. (1) A ternary system $G = (G, \eta)$ (Definition 1(3)) is a homogeneous pre-system if and only if the ternary operation η satisfies

$$\eta(x, y, x) = y, \quad \forall x, y \in G, \quad (3.1)$$

$$\eta(x, y, \eta(u, v, w)) = \eta(\eta(x, y, u), \eta(x, y, v), \eta(x, y, w)), \quad (3.2)$$

for all $x, y, u, v, w \in G$.

(2) A homogeneous system $G = (G, \eta)$ [18] is a homogeneous pre-system satisfying

$$\begin{aligned}\eta(x, x, y) &= y, \quad \forall x, y \in G, \\ \eta(x, y, \eta(y, x, z)) &= z, \quad \forall x, y, z \in G.\end{aligned} \quad (3.3)$$

We explain two examples in this section: one homogeneous pre-system and one homogeneous system, which imply dynamical Yang-Baxter maps in the next section.

Let G be an abelian group. We define the ternary operation η on G by

$$\eta(x, y, z) = x + y - z, \quad x, y, z \in G. \quad (3.4)$$

A trivial verification shows that $G = (G, \eta)$ is a homogeneous pre-system, which is not always a homogeneous system because of (3.3) (cf. [18, Remark 4]).

Another example is a homogeneous system on an arbitrary group G [18, Example in Section 1]. We define the ternary operation η on the group G by

$$\eta(x, y, z) = yx^{-1}z, \quad x, y, z \in G. \quad (3.5)$$

It is clear that this $G = (G, \eta)$ is a homogeneous system.

Remark 8. The homogeneous system (G, η) (3.5) is equivalent to the notion of a torsor [25, 33, 36], also known as the principal homogeneous space, up to the choice of the unit element. Hence, the principal homogeneous space provides a homogeneous system.

4 A relation between dynamical Yang-Baxter maps and homogeneous pre-systems

In this section, we construct dynamical Yang-Baxter maps (2.6) by means of homogeneous pre-systems $G = (G, \eta)$ satisfying

$$\eta(x, y, z) = \eta(w, \eta(x, y, w), z), \quad \forall x, y, z, w \in G. \quad (4.1)$$

In fact, we present a category \mathcal{H} concerning the homogeneous pre-systems with (4.1); this \mathcal{H} is isomorphic to the category \mathcal{A} in Section 2, and, on account of Theorem 6, every object of \mathcal{H} consequently gives a dynamical Yang-Baxter map.

Let $L = (L, \cdot)$ be a left quasigroup, $G = (G, \eta)$ a homogeneous pre-system satisfying (4.1) and $\pi : L \rightarrow G$ a (set-theoretic) bijection. The object of \mathcal{H} is a triple (L, G, π) .

The morphism $f : (L, (G, \eta), \pi) \rightarrow (L', (G', \eta'), \pi')$ of \mathcal{H} is a homomorphism $f : L \rightarrow L'$ of left quasigroups such that $h := \pi' \circ f \circ \pi^{-1} : G \rightarrow G'$ is a homomorphism of ternary systems; that is, the map $f : L \rightarrow L'$ satisfies (2.9) and

$$h(\eta(x, y, z)) = \eta'(h(x), h(y), h(z)), \quad \forall x, y, z \in G.$$

Proposition 9. *\mathcal{H} is a category; the definitions of the identity, the source, the target and the composition are similar to those of the category \mathcal{A} .*

In order to prove that the category \mathcal{H} is isomorphic to the category \mathcal{A} , we construct functors $F : \mathcal{A} \rightarrow \mathcal{H}$ and $F' : \mathcal{H} \rightarrow \mathcal{A}$.

We first introduce the functor $F : \mathcal{A} \rightarrow \mathcal{H}$. Let $(L, (M, \mu), \pi) \in \mathcal{A}$. Define the ternary system $G = (G, \eta)$ by $G = M$ as sets and

$$\eta(x, y, z) = \mu(y, x, z), \quad x, y, z \in G (= M). \quad (4.2)$$

Proposition 10. $(L, G, \pi) \in \mathcal{H}$.

Proof. We need only show that G is a homogeneous pre-system satisfying (4.1).

An easy computation shows (3.1) and (4.1).

By virtue of (4.2), the left-hand side of (3.2) is $\mu(y, x, \mu(v, u, w))$, and, with the aid of (2.2), (2.7) and (2.8),

$$\begin{aligned} \mu(y, x, \mu(v, u, w)) &= \mu(\mu(y, x, v), v, \mu(v, u, w)) \\ &= \mu(\mu(y, x, v), \mu(\mu(y, x, v), v, u), \mu(\mu(\mu(y, x, v), v, u), u, w)) \\ &= \mu(\mu(y, x, v), \mu(y, x, u), \mu(y, x, w)), \end{aligned}$$

which is the right-hand side of (3.2). This proves the proposition. \square

By setting $F(L, (M, \mu), \pi) = (L, G, \pi)$ and $F(f) = f$ for a morphism f of \mathcal{A} , the following proposition holds.

Proposition 11. $F : \mathcal{A} \rightarrow \mathcal{H}$ is a functor.

The next task is to construct a functor $F' : \mathcal{H} \rightarrow \mathcal{A}$. Let $(L, (G, \eta), \pi) \in \mathcal{H}$. We define the ternary system $M_G = (M_G, \mu)$ by $M_G = G$ as sets and

$$\mu(a, b, c) = \eta(b, a, c), \quad a, b, c \in M_G (= G). \quad (4.3)$$

Proposition 12. $(L, M_G, \pi) \in \mathcal{A}$.

Proof. It suffices to prove that M_G satisfies (2.2), (2.7) and (2.8).

A trivial verification shows (2.7) and (2.8).

Due to (4.1) and (4.3), the left-hand side of (2.2) is

$$\mu(a, \mu(a, b, c), \mu(\mu(a, b, c), c, d)) = \eta(\eta(b, a, c), a, \eta(b, a, d)).$$

From (3.1) and (3.2),

$$\eta(\eta(b, a, c), a, \eta(b, a, d)) = \eta(\eta(b, a, c), \eta(b, a, b), \eta(b, a, d)) = \eta(b, a, \eta(c, b, d)),$$

which is exactly the right-hand side of (2.2). \square

By setting $F'(L, (G, \eta), \pi) = (L, M_G, \pi)$ and $F'(f) = f$ for a morphism f of \mathcal{H} , the following proposition holds.

Proposition 13. $F' : \mathcal{H} \rightarrow \mathcal{A}$ is a functor:

Since the functors F and F' satisfy $F'F = \text{id}_{\mathcal{A}}$ and $FF' = \text{id}_{\mathcal{H}}$, the following theorem holds.

Theorem 14. The categories \mathcal{A} and \mathcal{H} are isomorphic.

By taking account of Theorem 6, we have the following corollary.

Corollary 15. Each object of \mathcal{H} provides a dynamical Yang-Baxter map.

The proof of the following proposition is straightforward.

Proposition 16. The ternary operations (3.4) and (3.5) satisfy (4.1).

As a consequence of Corollary 15 and Proposition 16, the homogeneous pre-system G (3.4) and the homogeneous system G (3.5) imply dynamical Yang-Baxter maps. Let $L = (G, \cdot)$ denote the left quasigroup whose binary operation (\cdot) is defined by

$$u \cdot v = v, \quad u, v \in L, \quad (4.4)$$

and let $\pi : L(= G) \rightarrow G$ be the identity map on G . The corresponding dynamical Yang-Baxter maps are as follows: if G is a homogeneous pre-system (3.4), then

$$R^{(L, M_G, \pi)}(\lambda)(u, v) = (v, \lambda + u - v), \quad \lambda, u, v \in L(= G),$$

and if G is a homogeneous system (3.5), then

$$R^{(L, M_G, \pi)}(\lambda)(u, v) = (v, \lambda u^{-1}v), \quad \lambda, u, v \in L(= G).$$

5 A relation between homogeneous pre-systems and left quasigroups

Because of the work in [32, Section 6] and the fact that the categories \mathcal{A} and \mathcal{H} are isomorphic, every homogeneous pre-system G (Definition 7(1)) in the object $(L, G, \pi) \in \mathcal{H}$ is a left quasigroup (Definition 1(1)) whose binary operation gives the ternary operation of G . This last section demonstrates it by constructing a category \mathcal{B} concerning the left quasigroups with (5.1) and an essentially surjective functor $J : \mathcal{B} \rightarrow \mathcal{H}$ (see [32, Proposition 6.17]). The functors $J : \mathcal{B} \rightarrow \mathcal{H}$, $S : \mathcal{A} \rightarrow \mathcal{D}$ in Section 2, and $F' : \mathcal{H} \rightarrow \mathcal{A}$ in Section 4, together with quasigroups of reflection [17, 27], provide examples of the dynamical Yang-Baxter map.

The first task is to introduce a category \mathcal{B} . Let $L_1, L_2 = (L_2, *)$ be left quasigroups. We assume that the left quasigroup L_2 satisfies

$$(a * c) \setminus_{L_2} ((a * b) * c) = (a' * c) \setminus_{L_2} ((a' * b) * c), \quad \forall a, a', b, c \in L_2. \quad (5.1)$$

Here the symbol \setminus_{L_2} is the left division (2.1) of L_2 . Let $\pi : L_1 \rightarrow L_2$ be a (set-theoretic) bijection. An object of \mathcal{B} is such a triple (L_1, L_2, π) .

A morphism $f : (L_1, L_2, \pi) \rightarrow (L'_1, L'_2, \pi')$ is a homomorphism $f : L_1 \rightarrow L'_1$ of left quasigroups such that $\pi' \circ f \circ \pi^{-1} : L_2 \rightarrow L'_2$ is also a homomorphism of left quasigroups.

Proposition 17. \mathcal{B} is a category; the definitions of the identity, the source, the target and the composition are similar to those of the category \mathcal{A} .

The next task is to construct a functor $J : \mathcal{B} \rightarrow \mathcal{H}$. Let $(L_1, (L_2, *), \pi) \in \mathcal{B}$. We define the ternary system $G_{L_2} = (G_{L_2}, \eta_{L_2})$ by $G_{L_2} = L_2$ as sets and

$$\eta_{L_2}(x, y, z) = z * (x \setminus_{L_2} y), \quad x, y, z \in G_{L_2} (= L_2). \quad (5.2)$$

Proposition 18. $(L_1, G_{L_2}, \pi) \in \mathcal{H}$.

Proof. It suffices to prove that G_{L_2} is a homogeneous pre-system satisfying (4.1).

We give a proof only for (3.2) because the rest of the proof is straightforward. Let $x, y, u, v, w \in G (= L_2)$. From (5.2) we have

$$\begin{aligned}\eta_{L_2}(x, y, \eta_{L_2}(u, v, w)) &= (w * (u \setminus_{L_2} v)) * (x \setminus_{L_2} y) \\ &= (w * (x \setminus_{L_2} y)) * ((w * (x \setminus_{L_2} y)) \setminus_{L_2} ((w * (u \setminus_{L_2} v)) * (x \setminus_{L_2} y))).\end{aligned}\quad (5.3)$$

With the aid of (5.1), the right-hand side of (5.3) is

$$\begin{aligned}&(w * (x \setminus_{L_2} y)) * ((w * (x \setminus_{L_2} y)) \setminus_{L_2} ((w * (u \setminus_{L_2} v)) * (x \setminus_{L_2} y))) \\ &= (w * (x \setminus_{L_2} y)) * ((u * (x \setminus_{L_2} y)) \setminus_{L_2} ((u * (u \setminus_{L_2} v)) * (x \setminus_{L_2} y))) \\ &= (w * (x \setminus_{L_2} y)) * ((u * (x \setminus_{L_2} y)) \setminus_{L_2} (v * (x \setminus_{L_2} y))),\end{aligned}$$

which is exactly $\eta_{L_2}(\eta_{L_2}(x, y, u), \eta_{L_2}(x, y, v), \eta_{L_2}(x, y, w))$. This is the desired conclusion. \square

Let $f : (L_1, L_2, \pi) \rightarrow (L'_1, L'_2, \pi')$ be a morphism of the category \mathcal{B} . The map $f : L_1 \rightarrow L'_1$ is a homomorphism of left quasigroups. Moreover, $h := \pi' \circ f \circ \pi^{-1} : L_2 \rightarrow L'_2$ is a homomorphism of ternary systems from G_{L_2} to $G_{L'_2}$, because h is a homomorphism of left quasigroups. As a result, $f : (L_1, L_2, \pi) \rightarrow (L'_1, L'_2, \pi')$ is a morphism of the category \mathcal{H} .

We set $J(L_1, L_2, \pi) = (L_1, G_{L_2}, \pi)$ for $(L_1, L_2, \pi) \in \mathcal{B}$ and $J(f) = f$ for a morphism f of \mathcal{B} .

Proposition 19. $J : \mathcal{B} \rightarrow \mathcal{H}$ is a functor.

This functor J is essentially surjective. In fact, for any $(L, G, \pi) \in \mathcal{H}$, we can construct a left quasigroup L_2 such that $(L, L_2, \pi) \in \mathcal{B}$ and $J(L, L_2, \pi) = (L, G, \pi)$. We fix any element $\lambda_0 \in G$. Set $L_2 = G$ as sets and

$$a * b = \eta(\lambda_0, b, a), \quad a, b \in L_2 (= G). \quad (5.4)$$

Due to (3.1) and (4.1), L_2 is a left quasigroup; its left division is defined by

$$a \setminus_{L_2} c = \eta(a, c, \lambda_0), \quad a, c \in L_2. \quad (5.5)$$

Proposition 20. $(L, L_2, \pi) \in \mathcal{B}$.

Proof. We need only show (5.1). Let $a, a', b, c \in L_2 (= G)$. With the aid of (5.4) and (5.5) we have

$$(a * c) \setminus_{L_2} ((a * b) * c) = \eta(\eta(\lambda_0, c, a), \eta(\lambda_0, c, \eta(\lambda_0, b, a)), \lambda_0). \quad (5.6)$$

From (3.2) and (4.1),

$$\begin{aligned}\eta(\lambda_0, c, \eta(\lambda_0, b, a)) &= \eta(\lambda_0, c, \eta(a', \eta(\lambda_0, b, a'), a)) \\ &= \eta(\eta(\lambda_0, c, a'), \eta(\lambda_0, c, \eta(\lambda_0, b, a')), \eta(\lambda_0, c, a)).\end{aligned}$$

By taking into account (4.1) again, the right-hand side of (5.6) is

$$\eta(\eta(\lambda_0, c, a), \eta(\lambda_0, c, \eta(\lambda_0, b, a)), \lambda_0) = \eta(\eta(\lambda_0, c, a'), \eta(\lambda_0, c, \eta(\lambda_0, b, a')), \lambda_0),$$

which is exactly the right-hand side of (5.1) by virtue of (5.4) and (5.5). This proves the proposition. \square

It is immediate that $J(L, L_2, \pi) = (L, G, \pi)$, and consequently, the following holds.

Proposition 21. The functor $J : \mathcal{B} \rightarrow \mathcal{H}$ is essentially surjective.

Corollary 22. The functor $SF'J : \mathcal{B} \rightarrow \mathcal{D}$ is essentially surjective.

The final task of this section is to construct dynamical Yang-Baxter maps by means of the functor $SF'J : \mathcal{B} \rightarrow \mathcal{D}$ and quasigroups of reflection; see [17, Section 1].

Definition 23. A pair $(G, *)$ of a nonempty set G and a binary operation $(*)$ on G is called a quasigroup of reflection if and only if $(G, *)$ is a left quasigroup (Definition 1(1)) satisfying

$$x * x = x, \quad \forall x \in G,$$

$$(x * y) * y = x, \quad \forall x, y \in G, \quad (5.7)$$

$$(x * y) * z = (x * z) * (y * z), \quad \forall x, y, z \in G. \quad (5.8)$$

It follows from (5.7) that $(G, *)$ is a quasigroup (Definition 1(2)).

Remark 24. (1) The above definition is slightly different from that in [17] (see also [26, II.1.1] and [27, Section 1]); the order of the binary operation $(*)$ on G is reversed.

(2) The identity (5.8) is called a right distributive law [30, Section V.2].

(3) The quasigroup of reflection gives an involutory quandle [1, 12, 37] by reversing the order of the binary operation in Definition 23.

A straightforward computation shows that Nobusawa's quasigroup $(Q, *)$ in Example 2 is a quasigroup of reflection.

Let $(G, *)$ be a quasigroup of reflection, and L a left quasigroup isomorphic to G as sets. We denote by π a set-theoretic bijection from L to G . Because (5.8) immediately induces (5.1),

Proposition 25. $(L, G, \pi) \in \mathcal{B}$.

The quasigroup $G = (G, *)$ of reflection hence produces the dynamical Yang-Baxter map $R(\lambda)$ defined by $(L, R) = SF'J(L, G, \pi) \in \mathcal{D}$.

For example, let $L = (G, \cdot)$ denote the left quasigroup (4.4) and $\pi : L(= G) \rightarrow G$ the identity map on G . The above dynamical Yang-Baxter map $R(\lambda)$ induced by $(L, G, \pi) \in \mathcal{B}$ is

$$R(\lambda)(u, v) = (v, v * (u \setminus_G \lambda)), \quad \lambda, u, v \in L(= G). \quad (5.9)$$

For Nobusawa's quasigroup $Q = (Q, *)$, the corresponding dynamical Yang-Baxter map (5.9) is really dependent on the parameter λ ; in fact,

$$R(1)(1, 1) = (1, 1), \quad R(2)(1, 1) = (1, 2).$$

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